12-1-2013

Design and Fabrication of an Infrared Optical Pyrometer Asic as a Diagnostic for Shock Physics Experiments

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DESIGN AND FABRICATION OF AN INFRARED OPTICAL PYROMETER ASIC
AS A DIAGNOSTIC FOR SHOCK PHYSICS EXPERIMENTS

By

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A thesis submitted in partial fulfillment
of the requirements for the

Master of Science in Electrical Engineering

Department of Electrical and Computer Engineering
College of Engineering
The Graduate College

University of Nevada Las Vegas
December 2013
We recommend the thesis prepared under our supervision by

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entitled

Design and Fabrication of an Infrared Optical Pyrometer Asic as a Diagnostic for Shock Physics Experiments

is approved in partial fulfillment of the requirements for the degree of

Master of Science in Electrical Engineering
Department of Electrical and Computer Engineering

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December 2013
ABSTRACT

Optical pyrometry is the sensing of thermal radiation emitted from an object using a photoconductive device to convert photons into electrons, and is an important diagnostic tool in shock physics experiments. Data obtained from an optical pyrometer can be used to generate a blackbody curve of the material prior to and after being shocked by a high speed projectile. The sensing element consists of an InGaAs photodiode array, biasing circuitry, and multiple transimpedance amplifiers to boost the weak photocurrent from the noisy dark current into a signal that can eventually be digitized. Once the circuit elements have been defined, more often than not commercial-off-the-shelf (COTS) components are inadequate to satisfy every requirement for the diagnostic, and therefore a custom application specific design has to be considered. This thesis outlines the initial challenges with integrating the photodiode array block with multiple COTS transimpedance amplifiers onto a single chip, and offers a solution to a comparable optical pyrometer that uses the same type of photodiodes in conjunction with a re-designed transimpedance amplifier integrated onto a single chip. The final design includes a thorough analysis of the transimpedance amplifier along with modeling the circuit behavior which entails schematics, simulations, and layout. An alternative circuit is also investigated that incorporates an approach to multiplex the signals from each photodiode onto one data line and not only increases the viable real estate on the chip, but also improves the behavior of the photodiodes as they are subjected to less thermal load. The optical pyrometer application specific integrated circuit (ASIC) for shock physics experiments includes a transimpedance amplifier (TIA) with a 100 kΩ gain operating at
bandwidth of 30 MHz, and an input-referred noise RMS current of 50 nA that is capable of driving a 50 Ω load.
ACKNOWLEDGEMENTS

My family means everything to me, and without their unconditional love and continued support I do not think I could have ever done this. I especially thank my wife for having to put up with my obsession with work and school. This will only be worth it if it makes me a better husband and father. I would also like to thank my coworkers who have provided such great insight, and have given me the perspective to continue on with my studies. Especially Tom Waltman, who was instrumental in me pursuing this type of research. I cannot thank him enough for how supportive he has been. Certainly I could never forget thanking Jake Baker. Dr. Baker has served as my professor, thesis adviser, but most of all as a friend. His instruction and guidance made what I considered a year ago as a hopeless endeavor all the more possible. There has not been a single moment during my long nights of writing when I felt any of this work to be a burden, and I believe much of that has to do with Jake showing me the bigger picture of what will be pursued and accomplished in years to come. This research will continue because of the need for technological innovation at work, the willingness of those that I work with, the foresight of my committee, and the tenacity of those wanting to see this through. For all of these things and much more, I truly thank you all.
DEDICATION

For my wife Janae, my son Ethan, and my daughters Gabrielle and Layla,

you are my inspiration.

I love you.
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CHAPTER 1 – INTRODUCTION

1.1 BACKGROUND

In shock wave physics experiments, dynamic temperature measurements are a critical diagnostic tool that provides valuable information about a material’s state under shock conditions [1]. To get real-time, in-situ temporal measurements, the diagnostic has to map the shape of the black body temperature curve at multiple wavelengths within a short record length. The basic elements of the diagnostic system include a photodiode transducer to convert infrared thermal radiation to electricity, a transimpedance amplifier (TIA) to convert the small photocurrent into a viable voltage signal, and an analog-to-digital converter (ADC) to record the signal. The focus of this Thesis is a subsection of the overall diagnostic system called an optical pyrometer which consists of an array of photodetectors and a transimpedance amplifier.

Limitations in current commercial-off-the-shelf (COTS) technology has shifted the focus away from assembling ad-hoc instrumentation with COTS components to designing application specific integrated circuits (ASICs) in order to meet the increasing design requirements of smaller footprints, higher bandwidth, and better noise performance. An optical pyrometer ASIC chip solves the current problems of integrating differing package types associated with the photodiode array sensing unit with multiple TIAs; moreover, it allows a certain amount of flexibility in designing around a set of requirements without sacrificing the performance from COTS components. In some cases an ASIC chip design will reduce the footprint of the instrument and increase its
performance. The integration of the photodiode array with COTS transimpedance amplifiers into an optical pyrometer instrument may increase the thermal loading on the photodiode array. Thermal loading is an important factor that has to be considered in any practical design as the photodiode package is susceptible to degradation in dynamic resolution as a consequence to sharing chip real estate with a set of transimpedance amplifiers. Without the knowledge \textit{a priori} of the type of data achievable from such experiments, that type of degradation in SNR can make the difference in the success of a diagnostic.

1.2 MOTIVATION

The implementation of a successful experimental diagnostic is limited more often than not by the technology that is available to both the scientist and engineer [2]. Many times there have been cases where a diagnostic cannot be fielded because an instrument has yet to be created to take the measurement of interest, or the COTS components that are available are unsuitable. Characteristics that include, biasing, noise immunity, form factor, and integration have to be carefully balanced in order to achieve a successful diagnostic. The constraint of having to utilize COTS components can severely impact the performance to the point where COTS are no longer a practical solution. This can result in an experiment being delayed indefinitely, which can be costly to a company or research lab.

Designing an optical pyrometer ASIC chip for shock physic experiments has two advantages. The first advantage is that new types of diagnostics instrumentation that
have not been created thus far can be created in current technology, and the other is that
the small form factor reduces the usable real estate in the test chamber thereby increasing
the number of measurements. The impact of this technology spans both science and
engineering fields. These types of instrumentation ASICs create vast opportunities in
materials science as \textit{in-situ} monitoring devices, and opens the door to analog and digital
chip designers who will be called upon to create innovative instrumentation designs.

1.3 THESIS ORGANIZATION

This Thesis describes the simulation, design, layout, and fabrication of an optical
pyrometer ASIC for shock physic experiments. Chapter 2 gives background information
on the photodiode, and emphasizes three different types that are likely to be used as the
sensing element in an optical pyrometer instrument. Chapter 3 provides a primer for the
TIA. Both the generic and improved TIA are discussed and compared in order to
demonstrate how simple adjustments can make significant improvements in the AC
performance. Concepts such as feedback, mixing-sampling topologies, and AC
characteristics that include open-loop and closed-loop gain are introduced. Calculations
of the AC parameters are compared with simulations in order to solidify the concepts.
Chapter 3 also discusses the TIA biasing circuitry, and introduces the cascode current
mirror. The chapter concludes with an encapsulation of the improved TIA closed-loop
gain. Chapter 4 covers the noise sources present in the optical pyrometer ASIC. Noise is
a limiting characteristic for any design, and this design is not an exception. Photodiode
shot noise, dark current, noise equivalent power, and MOSFET thermal and flicker noise
are all discussed. This chapter also discusses the noise modeling of the TIA along with simulations of the output noise, and input-referred noise of the improved TIA topology. Chapter 5 documents the testing of the improved TIA, and compares the test results with the results obtained through simulation. Differences in the testing and simulations results are discussed, and a final TIA design is proposed that addresses the shortcomings with the improved TIA. A discussion that includes simulations are included with the final TIA circuit. Chapter 6 provides additional background regarding the optical pyrometer’s role in shock physics experiments, and the reasons why a new design is needed. The chapter discusses a viable replacement option for the sensing transducer, and the final TIA chip layout. This chapter concludes with a plan for future work.
CHAPTER 2 – PHOTODIODE BACKGROUND

2.1 PN PHOTODIODE

The front-end of the optical pyrometer ASIC begins with the sensing element that converts infrared thermal radiation into an electrical signal. An ideal transducer for this task is a photodiode. A photodiode is comprised of a semiconductive material that is constructed into a pn junction with a heavily doped p-type material, and a lighter doped n-type material. A section of the pn diode, called the active area, is exposed to the environment to trap incident radiation. Figure 1 shows a cross sectional view of a pn photodiode.

![Figure 1. pn photodiode cross section](image)

Light incident upon the active area of the photodiode generates electron-hole pairs (EHPs) when the energy of the electromagnetic radiation is greater than the bandgap energy of the photoconductive material [3]. The photodiode has terminals on both sides of the junction and is usually reverse-biased. This implies that the p side of the junction is more negatively charged than the n side. The reverse-bias attracts the majority carriers...
away from the junction, which exposes the immobile ions in the depletion region, and
induces an electric field across the junction in a direction towards the p-type material [3, 4]. In this respect a photodiode takes on the characteristics of a voltage-controlled capacitor where the majority carriers behave as two sides of the parallel plates, and the depletion region acts as the dielectric gap. The depletion region, hence the electric field, penetrates deep into the n-region of the device because it is lightly doped. Any incident radiation capable of generating EHPs sweeps the pair by drifting them in opposing directions towards their respective majority carriers [3, 5]. The electrons are pushed out of the terminal thereby generating a photocurrent in an external circuit. An increase in the reverse-bias voltage increases the strength of the electric field within the depletion region of the device, and therefore increases the photocurrent. Not all of the incident electromagnetic radiation is absorbed into the active area, and not all of the radiation that is absorbed generates EHPs. Light below the material’s bandgap energy is absorbed and converted into heat, and light with energy above the bandgap energy does not imply an increase in the photocurrent. The excess energy of photons at a wavelength below the maximum cutoff wavelength will also be absorbed as heat by the lattice, and will not contribute to additional photocurrent. The cutoff wavelength \( \lambda(\mu m) \) for the conversion of light into electrons is given below

\[
\lambda(\mu m) = \frac{hc}{E_g(eV)} = \frac{1.24}{E_g(eV)} \quad (2-1)
\]

where \( E_g(eV) \) is the bandgap energy of the photoconductive material, and the constant \( hc = 1.24 \) is derived from \((4.14 \times 10^{-15} eV \cdot s) \cdot (3 \times 10^8 m/s)\) \(= 1.24 \times 10^{-6} eV \cdot m = 1.24 eV \cdot \mu m \) [5]. Near-infrared radiation has a wavelength of approximately
1.1 µm, so the minimum bandgap that a material must have in order to generate a photocurrent is

\[ E_G (eV) = \frac{1.24}{1.1\mu m} = 1.13 \text{ eV} \]  

(2-2)

Also, not all of the EHPs, generated by the absorbed radiation, are swept to their respective terminals. A small portion of the generated EHPs will recombine with each other, or become trapped within the defects of the material. The lost charges primarily contribute to lattice vibrations (phonons) that will act as noisy dark current limiting the dynamic range of the device [5]. Some of the light incident upon the active area reflects off the interface and is lost by the transducer. These factors and many others reduce the effectiveness of the device in converting light into an electrical signal thereby decreasing the quantum efficiency and responsivity of the photodiode.

One figure-of-merit for a photodiode is quantum efficiency. The equation for quantum efficiency \( \eta \) is shown below

\[ \eta = \frac{I_{ph}/e}{P_o/h \nu} \]  

(2-3)

where \( I_{ph} \) is the photocurrent in the external circuit due to the collection of electrons, \( e \), is the electronic charge (1.60 \( \times \) 10\(^{-19} \) C) in SI units, \( P_o \) is the incident optical power, \( h \) is Planck’s constant (6.62 \( \times \) 10\(^{-34} \) Js), and \( \nu \) is the electromagnetic radiation frequency [5]. Equation 2-3 gives a ratio of the number of electrons collected per second to the number of photons collected per second, and is a figure-of-merit for how efficient the photoconductive material is in converting light to electrons. The window of the photodiode contains an anti-reflective (AR) coating to prevent a significant percentage of
the light from reflecting off the active area, and is one common method utilized for increasing the quantum efficiency

Responsivity is another figure-of-merit for the photodiode that characterizes the conversion of light at a given wavelength into a photocurrent [5]. The equation for responsivity $\mathcal{R}$ is

$$\mathcal{R} = \frac{I_{ph}}{P_o} \quad (2-4)$$

2.2 PIN PHOTODIODE

Another way to increase the quantum efficiency of the photodiode is to sandwich an intrinsic layer between the highly doped p-region, $p^+$, and a highly doped n-region, $n^+$, of the pn junction diode. Figure 2 is a cross sectional view of a p-type/intrinsic/n-type (PIN) photodiode.

![PIN photodiode cross section](image)

Figure 2. PIN photodiode cross section [5].
Holes diffuse from the $p^+$-side and electrons diffuse from the $n^+$-side into the intrinsic layer where they recombine [5]. The depletion region generates a uniform electric field that is not present in a pn photodiode. The PIN photodiode is designed for photoabsorption to take place entirely within the intrinsic region [6]. Once the photodiode is reverse-biased, the depletion region extends through the entire intrinsic layer generating an electric field that sweeps the EHPs towards the $n^+$ and $p^+$ sides [6]. The increase in width of the depletion layer also increases the photogeneration area. Radiation with longer wavelengths can now contribute to the generation of EHPs since it is being absorbed within the depletion region. Another benefit of the PIN photodiode is the depletion capacitance is significantly smaller than the pn photodiode, and the small depletion capacitance allows the device to detect radiation at high modulation frequencies. The junction capacitance $C_J$ of the PIN photodiode is

$$C_J = \frac{K_S\varepsilon_0 A}{W} \quad (2-5)$$

where $K_S\varepsilon_0$ is the permittivity of the semiconductor, $W$ is the width of the depletion width, and $A$ is cross sectional area [6]. The width of the intrinsic layer is fixed, so the depletion capacitance does not depend on the applied voltage.

2.3 AVALANCHE PHOTODIODE

One significant drawback in both the pn junction and PIN photodiodes are the low responsivity levels. For the ideal photodiode, nothing more than what was put in could be expected out. The typical photodiode does not have gain, and this is problematic for
small photocurrent signals that are buried amongst the noise floor of the device or measuring system. An avalanche photodiode (APD) uses gain to amplify small light signals into measurable photocurrents. The gain mechanism for an APD is impact ionization. Strong electric fields, generated from large reverse-bias voltages, accelerate electrons into surrounding atoms, and impart enough energy to the constituent atoms that cause the ejection of additional electrons [7]. The ionization process continues until the energy of the electron is less than the electron binding energy of the atom. Avalanche multiplication implies that the quantum efficiency of the APD is greater than unity. Figure 3 shows an example cross-section for an APD.

In Figure 3, electromagnetic radiation enters through the window, the $p^+$ region, and stops within the intrinsic region of the device. EHPs are generated, within the intrinsic region (electron in the conduction band and a hole in the valence band) due to the interaction of the light with the crystalline structure. Photogeneration of EHPs and the avalanche multiplication are isolated processes within the APD because the multiplication is an inherently random process. This causes carrier fluctuation and leads to excess noise in the photocurrent signal thereby decreasing the signal-to-noise ratio (SNR) of the APD [5]. The reduction of the noise is achieved by decreasing the interaction probability that the carriers with the least impact ionization efficiency
(photogenerated holes) have with the electrons. The structure in Figure 3 allows the drifting of the photogenerated electrons to the avalanche region without the interaction of the holes. The avalanche multiplication factor, $M$ is given below

$$M = \frac{I_{ph}}{I_{pho}} \quad (2-6)$$

where $I_{ph}$ is the multiplied APD photocurrent, and $I_{pho}$ is the unmultiplied photocurrent [4, 5, 6, 7]. The multiplication factor can be obtained using the equation

$$M = \frac{1}{1 - \left(\frac{V_r}{V_{br}}\right)^n} \quad (2-7)$$

where $V_r$ is the reverse-bias voltage, $V_{br}$ is the avalanche breakdown voltage, and $n$ is a temperature dependent characteristic index that provides the best fit to the experimental data. Figure 4 shows a pictorial representation of avalanche multiplication.

![Avalanche multiplication pictorial representation](image)

Figure 4. Avalanche multiplication pictorial representation [5].
A transimpedance amplifier (TIA, a shunt-shunt feedback amplifier) generates a voltage signal at its output by amplifying a small current signal at its input of an active device. The units of the transfer function are therefore V/I (ohms) hence the name transimpedance amplifier or transresistance amplifier. TIAs use feedback to improve gain sensitivity, bandwidth, linearity, and output/input impedance. Figure 5 shows the basic topology of a shunt-shunt feedback amplifier for low-noise, low-power, and high-speed. The reason for calling the transimpedance amplifier shunt-shunt is that the feedback network $R_f$ is in parallel (shunt) with both the output of the amplifier and the input of the amplifier. The current input is connected to the source terminal of M1. The feedback network $R_f$ shunts some of the source current away from the input, and therefore the mixing of currents at the input active device M1 is known as shunt mixing. A similar analysis done at the output shows that again the feedback network is in parallel with the drain of the active device M2. In other words, the feedback network is in parallel with the amplifier’s output. Since any signal at the output of a feedback amplifier is sampled, the name used to describe this operation is called shunt sampling.
In an ideal transimpedance feedback amplifier, the feedback network will not load either the input or output of the amplifier and the equivalent impedance seen looking into input and output terminals of the amplifier is zero ohms. In other words, the ideal TIA has zero ohms input resistance (current input) and zero ohms output resistance (voltage output). When designing a practical transimpedance amplifier; however, the loading from the feedback network has to be taken into consideration. By using feedback techniques certain advantages can be exploited in controlling the input and output impedances. The input impedance $R_{lf}$, for the closed-loop transimpedance feedback amplifier

$$R_{lf} = \frac{R_i}{1 + \beta A_{OL}} \quad \text{(3-1)}$$

and the output in $R_{of}$, for the closed-loop feedback amplifier is
\[ R_{of} = \frac{R_o}{1 + \beta A_{OL}} \quad (3-2) \]

where \( \beta \) is the feedback factor (units of Mhos or Siemens), \( A_{OL} \) is the open-loop gain (units of ohms), \( \beta A_{OL} \) the loop gain (unitless), \( R_i \) the input impedance of the amplifier, and \( R_o \) is the output impedance of the amplifier \([8, 9]\). As \( A_{OL} \to \infty \), the input and output impedances of a feedback amplifier approach the ideal, that is, \( R_{if} = 0 \) and \( R_{of} = 0 \). The implication is that with a very large \( A_{OL} \) feedback is useful for reducing the TIA’s input/output impedances.

Inspection of the circuit in Figure 5 shows that the input active device M1 is biased with a constant DC voltage at the gate terminal. A current source, \( I_{ss} \), is used to ensure that the quiescent point remains constant as the small-signal AC current fluctuates. This current source, in more practical circuits, is replaced with a current mirror. M2 is the output active device that is driving the load which is in parallel with the feedback network. The voltage across the load resistor is being sampled, and feedback via \( R_f \). The feedback network \( R_f \), connects the drain of M2 to the source terminal of M1. A cursory analysis of the TIA in Figure 5 can be used to determine what type of feedback is employed. To ensure negative feedback by the number of signal inversions around the feedback loop of the amplifier are counted \([8, 9]\). The general rule of thumb is that a signal enters either the gate or source terminal of the active device, and exits the drain or source. When a signal enters the gate terminal and exits the drain, an inversion occurs. An odd number of inversions imply negative feedback. In Fig.5 the input signal enters the source terminal of M1 and the output signal departs the drain terminal, so no inversion occurs. The signal that left the drain of M1 enters the gate of M2. This signal
leaves the drain of M2 and therefore there is only one inversion around the loop. Indeed this topology uses negative feedback.

Figure 6 is the open-loop, small-signal, model for the shunt-shunt amplifier circuit in Fig. 5. The open-loop small-signal model in Fig. 6 shows how the loading from the feedback network affects the shunt-shunt amplifier circuit. The equivalent resistance of the feedback network seen at the input of the amplifier is determined by looking into the input terminal of the feedback network while shorting the output to ground. The equivalent resistance of the feedback network seen at the output of the amplifier is determined by looking at the output terminal of the feedback network while shorting the input to ground. In both cases the equivalent resistance is the value of $R_f$. Now that the loading of the amplifier circuit by the feedback network has been factored into the small-signal model, the open-loop gain that relates the output voltage to the input current can be evaluated directly from Figure 6.

![Figure 6. Shunt-shunt feedback amplifier open-loop small-signal model.](image)

The open-loop gain is

$$A_{OL} = \frac{v_2^*}{i_3^*} = \frac{v_2^*}{v_{g2}^*} \cdot \frac{v_{g2}^*}{v_1^*} \cdot \frac{v_1^*}{i_3^*}.$$
\[
\begin{align*}
&= - \frac{g_{m2} R_L \| R_f \| (1 + g_{m2} R_4 r_{o2} + R_4)}{1 + g_{m2} R_4 + \frac{R_4}{r_{o2}}} \cdot \frac{g_{m1} R_3 + \frac{R_3}{r_{o1}}}{1 + \frac{R_3}{r_{o1}}} \cdot \left( \frac{1 + \frac{R_3}{r_{o1}}}{g_{m1} + \frac{1}{r_{o1}}} \right) || R_f \| \Omega \\
&= A_{OL} = - \frac{g_{m2} (R_L \| R_f)}{1 + g_{m2} R_4} \cdot g_{m1} R_3 \cdot \frac{1}{g_{m1}} \cdot || R_f \| \Omega 
\end{align*}
\]

when \( i_1^* = i_0^* \). Equation 3-3 simplifies to

\[
A_{OL} = - \frac{g_{m2} (R_L \| R_f)}{1 + g_{m2} R_4} \cdot g_{m1} R_3 \cdot \frac{1}{g_{m1}} \cdot || R_f \| \Omega 
\]

when \( r_{o2} \ll R_2, R_4, R_L \), and \( r_{o1} \ll R_3 \). The closed-loop gain, \( A_{CL} \), for the shunt-shunt
amplifier is

\[
A_{CL} = \frac{v_2}{i_s} = \frac{A_{OL}}{1 + \beta A_{OL}} \Omega 
\]

when \( i_s = i_1 \), and the feedback factor, \( \beta \), is

\[
\beta = \frac{i_1^*}{v_2^*} = - \frac{1}{R_f} \text{ mhos} 
\]

The feedback factor is the gain of the feedback network and is a negative value since the
output from the amplifier was previously determined to be negative. The loop gain,
\( \beta A_{OL} \), is a positive dimensionless quantity, so that is why the feedback factor has the
units of mhos since the transimpedance amplifier has units of ohms. An increase in the
loop gain or feedback factor will decrease the closed-loop gain of the TIA, and implies a
trade-off between the precision and gain of a feedback amplifier [10].

16
The input impedance is the equivalent impedance seen through the drain terminal of M1 in parallel with $R_f$, and the output impedance is the parallel combination of $R_f$, $R_L$, and the equivalent impedance seen looking into the drain of M2, therefore

$$R_i = \left(1 + \frac{R_3}{r_{o1}}\right)||R_f$$

$$R_o = R_L||R_f||\left(1 + g_{m2}R_4\right)$$

3.1 SHUNT-SHUNT FEEDBACK OPEN-LOOP GAIN VERIFICATION

Equation 3-8 is an exact calculation of the open-loop gain of the shunt-shunt feedback amplifier. However, there is a more practical method to determine the open-loop gain. Figure 7 shows the open-loop small-signal model of the shunt-shunt amplifier with the feedback network loading contribution on the output of M2. Notice that the current source, which is $I_{ss}$ in Fig. 5, is no longer present in Fig. 6. The current source and the output resistance of M1 have been replaced with a resistance called $R_{cas}$. This resistance is the equivalent resistance seen looking into the drain of the cascode circuit M1 and $I_{ss}$ (generated from a current mirror). To determine the open-loop gain the circuit can be broken down into two parts. In the first part the voltage $v_x$ has to be determined, and the second part consists of finding the gain $v_{out}/v_x$. The voltage $v_x$ is calculated from the $i_l$ current flowing into the parallel resistance of $R_3$ and $R_{cas}$. The cascode impedance is typically larger than the resistance used to generate the bias current of the TIA, so the voltage $v_x$ is approximated to
The output voltage is calculated from the current generated from M2 flowing into the impedance seen looking into the output terminal. The equivalent impedance at the output of M2 is the parallel combination of the load, feedback, and impedance looking into the drain of M2. This expression is

$$v_{x} = i_{i}(R_{3}||R_{cas}) \approx i_{i}R_{3} \quad (3-9)$$

The output voltage is calculated from the current generated from M2 flowing into the impedance seen looking into the output terminal. The equivalent impedance at the output of M2 is the parallel combination of the load, feedback, and impedance looking into the drain of M2. This expression is

$$v_{out} = i_{d}(R_{L}||R_{f}||r_{inDrainM2}) \quad (3-10)$$

Figure 8 demonstrates how to calculate the current $i_{d}$ from (3-10). A KVL equation is written from $R_{4}$ to $v_{x}$, and $i_{d}$ is solved as a function of $v_{x}$.

$$i_{d}R_{4} + v_{sg2} + v_{x} = 0 \quad (3-11)$$

$$i_{d} = g_{m2}v_{sg2} \rightarrow v_{sg2} = \frac{i_{d}}{g_{m2}} \quad (3-12)$$

Figure 7. Small-signal analysis to find $v_{x}$ in the generic shunt-shunt feedback amplifier.
\[ i_d = -\frac{v_x}{\frac{1}{g_{m2}}}R_4 \]  

(3-13)

Figure 8. Small-signal analysis to find \( v_{out}/v_x \) in the generic shunt-shunt feedback amplifier.

The circuit is redrawn in Fig. 9 to show how to calculate the impedance seen looking into the drain of M2. A test voltage is applied to the drain of M2. The current in \( R_L \parallel R_f \) is neglected since these are in parallel with the resistance looking into the drain of M2.
After substituting (3-16) and (3-17) into (3-15), an expression for \( v_t \) is calculated.

\[
v_t = i_t [r_{o2}(1 + g_{m2}R_4) + R_4]
\]

(3-18)

\[
\therefore r_{inDrainM2} = \frac{v_t}{i_t} = r_{o2}(1 + g_{m2}R_4) + R_4
\]

(3-19)

The open-loop gain for the shunt-shunt amplifier in Fig. 5 can now be determined after substituting (3-19), (3-13), and (3-9) into (3-10).
\[
|A_{OL}| = \frac{v_{out}}{i_l} \approx \frac{\langle R_L \rangle |R_f| \left[ \frac{1}{(1+g_{m2}R_4)r_{o2}+R_4} \right] \cdot R_3}{\frac{1}{g_{m2}+R_4}} \Omega \quad (3-20)
\]

3.2 GENERIC TIA SIMULATION

Figure 10 shows the simulation schematic of the open-loop gain for the generic TIA (a shunt-shunt feedback amplifier). A scale factor of 1\(\mu\)m is used, so the width for the PMOS and NMOS devices are 10 and 30 respectively. The lengths for both devices were set at 2\(\mu\)m. The low frequency gain of the circuit can be estimated from Equation 3-8, and according to the equation, the open-loop gain cannot be greater than \(R_f\), one over the feedback factor, \(\beta\). In order to verify that the open-loop gain is in part, determined by \(R_f\), a DC operational point and AC analysis will be performed. The results of the DC operational point analysis will give the numerical value for the transconductance, and the drain-source transconductance of M2 (the reciprocal of \(r_{o2}\)). Both the transconductance and \(r_{o2}\) of M2 will be inserted into Equation 25, and the calculated result will be compared with the AC plot of \(v_{out}/i_{in}\).
Figure 10. Generic TIA AC analysis schematic.

Figure 11 shows the operational point analysis results.

```
Circuit: *** SPICE deck for cell ACanalysis{sch} from library

Direct Newton iteration for .op point succeeded.
Semiconductor Device Operating Points:

--- MOSFET Transistors ---

        Name  mm2    mm1
Model  p1u   n1u
Id:  1.54e-05  2.00e-05
Vgs:  2.01e-01  1.07e+00
Vds:  1.87e+00  2.59e-01
Vth: -1.50e+00  8.47e-01
Vdsat: -2.08e-01  2.29e-01
Gm:  1.31e-04  1.36e-04
Gds:  1.98e-07  5.07e-07
Gmb:  1.65e-05  3.84e-05
Cbd:  0.00e+00  0.00e+00
Cbs:  0.00e+00  0.00e+00
CgsOV:  6.00e-15  2.00e-15
CgdOV:  6.00e-15  2.00e-15
CgboV:  1.80e-16  1.80e-16
Cgs:  0.00e+00  2.07e-14
Cgd:  6.21e-14  0.00e+00
Cgb:  0.00e+00  0.00e+00
```

Date: Mon Jul 22 20:27:00 2013
Total elapsed time: 0.090 seconds.

Figure 11. Generic TIA OP analysis results.
From these simulation results, the transconductance and drain-source resistance of M2 are listed under the name “mm2” in Fig. 11 and are:

\[ g_{m2} = Gm = 131 \mu A/V \quad (3-21) \]

\[ r_{o2} = \frac{1}{Gds} = \frac{1}{0.198 \mu S} = 5.05 \, M\Omega \quad (3-22) \]

Inserting both of these values into (3-20) gives

\[ |A_{OL}| = \frac{v_{out}}{i_i} \approx \frac{(5k||5k||[(1+131 \cdot 200k) \cdot 5.05M+200k]}{131+200k} \cdot 238k = 2.97 \, k\Omega \quad (3-23) \]

The plot of the open-loop gain from the AC analysis is shown in Fig. 12, and it shows that the low frequency open-loop gain for the TIA, \(\approx 2.6 \, k\Omega\), is in close agreement to the calculation in (3-23).

![Figure 12. Generic TIA open-loop gain plot from the AC analysis.](image)
3.3 IMPROVED TIA CIRCUIT

The TIA in Figure 5 is a fully functional circuit, but there are some simple improvements that can be done to increase the open-loop gain without adding to the complexity of the design. For instance, resistor $R_3$ can be replaced with a PMOS device. This has the effect of increasing a term in the numerator of equation (3-20) therefore increasing the open-loop gain while generating a constant biasing current that is more insensitive to changes in the power supply. The resistor $R_4$ can be replaced with a wire ($R_4 = 0$). This has the effect of increasing the open-loop gain since a term in the denominator of (3-20) is decreasing. The load resistance, $R_L$, in Figure 5 is replaced with an NMOS transistor. The addition of this device will further increase the open-loop gain of the TIA. Figure 13 shows the improved design. The feedback amplifier is biased with a diode-connected current mirror. Both an NMOS and PMOS current mirror are utilized to bias additional circuitry on the back-end of the TIA. The M3 and the M4 devices act as the PMOS and NMOS current mirrors respectively, and M1 behaves as the cascode. The cascode increases the output resistance of the current mirror [11]. This has the effect of creating an ideal current source by maintaining a constant voltage drop across the output of the mirror [11]. The biasing voltages for the circuit in Figure 13 are

\[ V_{biasn} = V_{GS} \]  \hspace{1cm} (3-24)

\[ V_{ncas} = V_{biasp} = 2V_{GS} \]  \hspace{1cm} (3-25)

Since the current mirror is a symmetric device, the drain voltages for M2 and M3 are

\[ V_{D2} = 2V_{GS} = V_{biasp} \]  \hspace{1cm} (3-26)
On the back end of the shunt-shunt feedback amplifier is another type of amplifier called a series-shunt (transconductance) feedback amplifier. This type of circuit series mixes the output voltage of the shunt-shunt feedback amplifier with the feedback signal from the output of the M8 transistor. Therefore the mixing taking place at the input active device M7 is series. The output of M8 consists of a parallel connection between the 50 Ohm load resistor (the amplifier's load), the drain of M8, and the source terminal of M7. This implies that the feedback network is shunting some of the current away from the output amplifier; hence the type of sampling at the output is referred to as shunt [12].

![Diagram of improved TIA design](image)

**Figure 13. Improved TIA design.**

The series-shunt feedback amplifier is considered a voltage amplification device with a gain having units V/V. In this topology, the voltage amplifier has to drive a 50 ohm load, but it does not have enough drive strength to do this directly, so eight PMOS transistors
are connected in parallel (the MOSFET is constructed with 8 fingers). The amplifier output sources much more current than the other devices solely for driving a 50 ohm load. This series-shunt feedback amplifier is designed to act as a voltage follower, and therefore it will have a voltage gain less than unity; however, the amplifier will have considerable current gain.

3.3.1 IMPROVED TIA OPEN-LOOP GAIN VERIFICATION

Recall that the open-loop gain for the generic shunt-shunt feedback amplifier in Figure 5 was already given in (3-20) and is restated below for convenience.

\[ |A_{OL}| = \frac{v_{out}}{i_{i}} \approx \left( \frac{R_{L}||R_{f}||\left[1+g_{m2}R_{4}\right]r_{o2}+R_{4}}{1+g_{m2}R_{4}} \right) R_{3} \Omega \]

In the improved design of the shunt-shunt feedback amplifier, the open-loop gain simplifies to

\[ |A_{OL}| = \frac{v_{out}}{i_{i}} \approx \left( \frac{r_{o5}||R_{f}||r_{o4}}{1/g_{m4}} \right) r_{o1} = g_{m4} \left( \frac{r_{o5}||R_{f}||r_{o4}}{1/g_{m4}} \right) \cdot r_{o1} \Omega \quad (3-28) \]

since \( g_{m4} = g_{m2}, R_{3} = r_{o1}, r_{o2} = r_{o1}, R_{L} = r_{o5}, \) and \( R_{4} = 0. \) Again, the improved design will have a larger gain than the generic design by virtue of the numerator/denominator of (3-28) increasing/decreasing.
To verify that the open-loop gain of the improved shunt-shunt feedback amplifier is indeed (3-28), a DC operating point analysis will be performed on the circuit in Fig. 13 to determine the transconductance and drain-source conductance (inverse of the conductance is resistance) for M4, and the drain-source conductances of M1 and M5.

The value calculated in equation (3-28) will be compared with the plot of the low frequency gain from an AC analysis. Table 3-1 shows the results of the MOSFET characteristics from the DC operational point analysis.

Table 3-1. Operational point analysis results for the improved TIA.

The transconductance of the PMOS device and the drain-source conductance for M4 are listed under the heading “mm4” and are given by:

\[ g_m = \frac{G_m}{V} = 3.02 \text{ mA/V} \quad (3-29) \]

\[ r_{ds} = \frac{1}{G_{ds}} = \frac{1}{0.117 \text{ mS}} = 8.55 \text{ k\Omega} \quad (3-30) \]
The drain-source conductances for M1 and M5 are listed under the headings “mm1” and “mm4” respectively.

\[ r_{o1} = \frac{1}{G_{ds}} = \frac{1}{0.177 \, mS} = 5.65 \, k\Omega \quad (3-31) \]

\[ r_{o5} = \frac{1}{G_{ds}} = \frac{1}{93.5 \, \mu S} = 10.7 \, k\Omega \quad (3-32) \]

Inserting (3-29) – (3-32) into (3-28), the open-loop gain is calculated as

\[ |A_{OL}| = \frac{v_{out}}{i_i} \approx g_m4 \left( r_{o5} \left| \frac{R_f}{r_{o4}} \right| r_{o1} \right) \cdot r_{o1} = \left( 3.02 \frac{mA}{V} \right) \cdot \left( 10.7k\Omega \left| 50k\Omega \right| 8.55k \right) \cdot 5.65k = 74.1 \, k\Omega \quad (3-33) \]

Figure 14 shows the plot of the open-loop gain (\(v_{out1}/i_{in}\)) for the improved shunt-shunt feedback amplifier.

![Figure 14. AC analysis plot of the open-loop gain for the improved shunt-shunt amplifier.](image)

The plot of the open-loop gain is in close agreement to the calculated value in (3-33).
Several other features that are worth looking into is verifying that the dc drain voltages for M2 and M3 of the current mirror are equal to (3-26) and (3-27) respectively. According to Fig.15:

<table>
<thead>
<tr>
<th></th>
<th>voltage</th>
</tr>
</thead>
<tbody>
<tr>
<td>( V_{d2} )</td>
<td>3.20547</td>
</tr>
<tr>
<td>( V_{biasp} )</td>
<td>3.16277</td>
</tr>
<tr>
<td>( V_{dd} )</td>
<td>5</td>
</tr>
<tr>
<td>( V_{d3} )</td>
<td>1.47315</td>
</tr>
<tr>
<td>( V_{biasn} )</td>
<td>1.46961</td>
</tr>
</tbody>
</table>

Figure 15. DC operating point nodal voltages.

\[
V_{D2} = 2V_{GS} = V_{bias} = 3.21V \quad (3-34)
\]

\[
V_{D3} = V_{GS} = V_{bias} = 1.47V \quad (3-35)
\]

The expected voltages at the drain of the cascode and current mirror are indeed verified through the results of the operational point analysis.

An AC analysis can also be performed on the series-shunt feedback amplifier to determine the open-loop gain of the circuit. Since it was previously determined that this particular topology is a voltage follower, intuitively the expectation is that the closed-loop voltage gain should be less than one, and with such a small closed-loop gain, the expectation is that the open-loop gain will also be small, but larger than unity. In order to find an expression for the voltage follower gain, the circuit is reconstructed in Fig. 16 as a small-signal model.
Notice that since the desired response is the open-loop gain, the feedback connection is shorted to ground at the input, but the connection is opened at the output. Anytime that there is series mixing or sampling, the feedback network will be shorted to ground; moreover, for shunt mixing or sampling, the feedback network will be opened. Any gain in the path of the feedback network will load both the input and output active devices, and the model will have to reflect those loading effects. For the circuit in Fig.16 there are no loading effects at the input or output because there is no gain in the feedback network.

The voltage at the output is given by

\[ v_{out2} = i_{d8}(r_{o8}||R_L) \]  \hspace{1cm} (3-36)

The current generated by M8 is

\[ i_{d8} = g_{m8}v_{SGB} = -g_{m8}v_y \]  \hspace{1cm} (3-37)

Inserting (3-37) into (3-36) gives
\[ v_{out2} = -g_{m8}v_y(r_{o8}||R_L) \quad (3-38) \]

An expression for \( v_y \), and the current generated by M7 are:

\[ v_y = i_d7(r_{o6}||r_{o7}) \quad (3-39) \]

\[ i_{d7} = g_{m7}V_{GS7} = g_{m7}v_{out1} \quad (3-40) \]

Plugging (3-40) and (3-39) into (3-38) to form the expression as

\[ |A_{OL}| = \frac{v_{out2}}{v_{out1}} = g_{m8}(g_{m7}(r_{o6}||r_{o7}))(r_{o8}||R_L) \quad (3-41) \]

Table 2-1 still gives the correct values that are required to calculate the open-loop gain since reconstructing the circuit in Figure 15 does not alter the DC characteristics. Below are the results that are needed for (3-41):

\[ g_{m7} = Gm = 3.03 \frac{mA}{V} \quad (3-42) \]

\[ g_{m8} = Gm = 19.0 \frac{mA}{V} \quad (3-43) \]

\[ r_{o6} = \frac{1}{G_{ds}} = \frac{1}{0.238 \text{ ms}} = 4.20 \text{ k}\Omega \quad (3-44) \]

\[ r_{o7} = \frac{1}{G_{ds}} = \frac{1}{55.1 \mu\text{s}} = 18.1 \text{ k}\Omega \quad (3-45) \]

\[ r_{o8} = \frac{1}{G_{ds}} = \frac{1}{0.497 \text{ ms}} = 2.01 \text{ k}\Omega \quad (3-46) \]

Inserting (3-46) – (3-42) into (3-41) gives

\[ |A_{OL}| = \frac{v_{out2}}{v_{out1}} = \left( 19.0 \frac{mA}{V} \right) \left( 3.03 \frac{mA}{V} \right) \cdot (4.20\text{ k}\Omega \cdot 18.1\text{ k}\Omega) (2.01\text{ k}\Omega \cdot 50) = 9.6 \quad (3-47) \]
Comparing the calculated value with the plot in Fig.17, the open-loop gain is reasonably close.

![AC analysis plot of the open-loop gain for the series-shunt amplifier.](image)

Figure 17. AC analysis plot of the open-loop gain for the series-shunt amplifier.

The schematic that was used for the AC analysis is shown in Fig.18. Notice that the circuit had to be altered in order to determine the open-loop gain by simulation. The inductor at the gate of M7 allows the DC biasing from the shunt-shunt amplifier to maintain the bias point, and the capacitor AC couples the input signal to the input of the amplifier. Also, the inductor in the feedback path blocks any feedback from the output amplifier, and the capacitor is added to ensure that M7 has an AC path to ground.
3.3.2 IMPROVED TIA DESIGN ENCAPSULATION

In the previous section emphasis was placed on how to take a rudimentary design, such as the generic TIA, and make vast improvements with low complexity changes. In this section not much has been discussed about the entire circuit when analyzed as a whole. When characterizing these types of systems the open-loop gain and the feedback factor are the only relevant parameters because the loop gain is the most important characteristic in a feedback amplifier [13]. Once all of these parameters are determined, the gain of the system can be calculated. Up to this point, the open-loop gain for two devices that comprise the improved TIA have been calculated and simulated, but the closed-loop gain for both circuits have not. Recall that the closed-loop gain is 3-10 and is shown below for convenience.

Figure 18. AC analysis schematic of the open-loop gain for the series-shunt amplifier.
\[ A_{CL} = \frac{A_{OL}}{1 + \beta A_{OL}} \]

For the improved shunt-shunt amplifier, the closed-loop gain is

\[ A_{CL} = \frac{A_{OL}}{1 + \beta A_{OL}} = \frac{-74.1 \ k\Omega}{1 + \frac{1}{50 \ k\Omega} \cdot -74.1 \ k\Omega} = -29.9 \ k\Omega \quad (3-48) \]

given that the feedback factor is

\[ \beta = \frac{-1}{R_f} = -\frac{1}{50 \ k\Omega} \text{ mhos} \quad (3-49) \]

The closed-loop gain is much less than the 50 kΩ because the open-loop gain of the improved TIA is not infinitely large. Figure 19 shows the plot of the closed-loop gain for the improved shunt-shunt feedback amplifier.

Figure 19. AC analysis plot of the closed-loop gain for the shunt-shunt amplifier.

The calculated value, and the plot of the closed-loop gain are in close agreement. The closed-loop gain of the voltage follower is
\[ A_{CL} = \frac{A_{OL}}{1+\beta A_{OL}} = \frac{9.6}{1+(1)(9.6)} = 0.91 \quad (3-50) \]

given that \( \beta = 1 \). Figure 20 shows a plot of the closed-loop gain of the voltage follower.

![Figure 20. AC analysis plot of the closed-loop gain for the series-shunt amplifier.](image)

Both the calculation and the plot are in close agreement. For the entire TIA circuit, the closed-loop gain is the product of the gain from the shunt-shunt feedback circuit and the series-shunt feedback circuit.

\[ A_{CL} = -29.9 \, k\Omega \times 0.91 = -27.2 \, k\Omega \quad (3-51) \]

Figure 21 shows the plot of the closed-loop gain for the TIA, and the results are in close agreement. Notice how the closed-loop gain of the TIA is smaller than the open-loop gain. One of the disadvantages in incorporating negative feedback is the reduction in gain in order to achieve an increase in bandwidth, stability, and linearity.
Figure 21. AC analysis plot of the closed-loop gain for the TIA.
CHAPTER 4 – NOISE

Noise in the most simplistic definition is any unwanted signal that degrades or interferes with a desired signal. Electrical noise is commonly understood as the random thermal fluctuations of electron motion in conductors, but electrical noise is also the random movement of charge across a discontinuity. This is the case with leakage current at the gate-oxide interface of metal-oxide semiconductor field-effect transistors (MOSFETs), and is referred to as shot noise. The effects of noise in electrical circuits can be heard in the crosstalk interference from a two-way radio, the humming from a transformer, the flicker of a picture on a television screen, and the fluctuations seen with a signal on an oscilloscope. Noise has an additive and random component, and there is no method that exists to eliminate it altogether. The best that can be done is to minimize the effects of noise on the system, but with all designs there are associated costs. Speed and bandwidth are often affected when noise minimization techniques are employed. As in any design tradeoffs have to be considered.

In the optical pyrometer ASIC there are several types of noise sources that can influence the integrity of the desired signal. The predominant noise sources include thermal noise in any of the discrete resistors that are used for biasing the photodiode or for setting the gain in the feedback amplifiers, shot noise present within the photodiode and MOSFETs, and flicker and thermal noise in the short-channel MOSFETS (channel lengths less than 1 \( \mu \)m) that comprise the TIA circuit. This chapter will discuss all of the dominant noise sources in the optical pyrometer ASIC chip, and will include the techniques that are used to model noise in simulations. The calculation of the input-
referred noise in the improved TIA circuit along with a noise simulation to verify the calculation will also be given in this section.

4.1 THERMAL NOISE

Thermal noise, or Johnson noise, is associated with the random motion of charge in a conductor, and is governed by temperatures above absolute zero. There is no overall contribution in net current from all of the carriers undergoing random thermal motion; however, at any finite interval in time, there are nonzero changes in the net current [14]. The equation that defines the power spectral density (PSD) of thermal noise is shown below

\[ V_R^2(f) = 4kTR \ (V^2/Hz) \quad (4-1) \]

where \( k \) is Boltzmann’s constant, which is \( 13.8 \times 10^{-24} J \cdot \circ K^{-1} \). \( T \) is temperature in degrees Kelvin, or \( \circ K \), and \( R \) is the resistance in ohms (\( \Omega \)) [14]. One characteristic that is obvious from (4-1) is that the thermal noise PSD is constant over any bandwidth. A signal that occupies the entire frequency spectrum, and has a near constant PSD is called white noise because it is similar to white light whose spectral content is also constant over the visible spectrum. A spectrum analyzer (SA) is used to measure the thermal noise in a circuit. The results of the noise analysis may give small output noise values, but in many cases, in an exceptionally designed system, that value provides a wealth of information. If thermal noise was the only source of noise present within the system, then the output PSD shows the noise floor for that system. Suppose that the system was a
digitizer, then knowing the noise floor implies knowing the smallest signal that can be digitized. The circuit models for thermal noise are shown below in Fig.22.

\[ V_R(f) = \sqrt{4kT} \]

\[ I_R(f) = \frac{4kT}{R} \]

Figure 22. Thermal noise models.

The units for the voltage spectral density, \( V_R(f) \), are \( V/\sqrt{Hz} \), and \( A/\sqrt{Hz} \) for \( I_R(f) \). At room temperature, approximately 300 K, the value for \( 4kT \) approximates to

\[ 4kT = 4 \cdot (13.8 \times 10^{-24} J \cdot ^oK^{-1}) \cdot 300K \approx 1.66 \times 10^{-20} J \quad (4-2) \]

The mean-squared RMS output noise voltage for the current noise model is

\[ V_{\text{noise,RMS}}^2 = \int_{f_1}^{f_2} \frac{4kT}{R} \cdot R^2 \, df = 4kTRB \ (Volts^2) \quad (4-3) \]

where \( B = f_2 - f_1 \ Hz \). To reduce the thermal RMS output noise in a system, the practical solution is to limit its overall bandwidth.

A MOSFET has thermal noise associated with the resistance in the channel [14]. The thermal noise is different if the MOSFET is operating in the triode or saturation region. In the saturation region, the thermal noise PSD is

\[ I_{R,MOS}^2(f) = \frac{4kT}{\frac{3}{2} g_m} = \frac{8kT}{3} \cdot g_m \ A^2/Hz \quad (4-4) \]
The thermal noise PSD for a MOSFET operating in the triode region is

\[ I_{R,MOS}^2(f) = \frac{4kT}{R_{ch,triode}} \frac{A^2}{Hz} \]  

(4-5)

A photodiode also has a thermal noise contribution, but it has more to do with the biasing than the actual photodiode. The photodiode is modeled as an parallel RC circuit in simulation. Figure 23 shows the model of the shot noise.

![Figure 23. Shot noise model.](image)

The resistance in the RC circuit is added to bias the photodiode, and the capacitance models the depletion capacitance for a reverse biased diode. This capacitance \( C_{dep} \) is a function of the biasing voltage is described by

\[ C_{dep} = \frac{C_{j0}}{\left(1 + \frac{V_d}{V_{bi}}\right)^m} \]  

(4-6)

where \( C_{j0} \) is the zero-bias depletion layer capacitance, \( V_d \) is the voltage across the diode, \( V_{bi} \) is the built-in potential, and \( m \) is the grading coefficient [8]. According to Fig. 23,
the output noise has a single-pole rolloff, so the RMS voltage output noise for the photodiode element in the optical pyrometer ASIC chip is

\[ V_{\text{shot,RMS}} = \sqrt{\frac{kT}{C}} \]  \hspace{1cm} (4-7)

This is commonly referred as “kay tee over cee” noise. To verify that the photodiode has an RMS output noise given by equation (4-7), the output noise is described as

\[ V_{\text{noise}}(f) = \sqrt{\frac{4kT}{R} \cdot \left[ \frac{\frac{1}{\omega C_{\text{dep}}}}{R + \frac{1}{j\omega C_{\text{dep}}}} \right]} = \sqrt{\frac{4kT}{R} \cdot \left[ \frac{R}{1 + j\omega RC_{\text{dep}}} \right]} \]  \hspace{1cm} (4-8)

\[ V_{\text{noise}}^2(f) = \frac{4kT}{R} \cdot \left[ \frac{\left[ \frac{R}{1 + \left( \frac{f}{f_{3dB}} \right)^2} \right]^2}{1 + \left( \frac{f}{f_{3dB}} \right)^2} \right] = \frac{4kTR}{1 + \left( \frac{f}{f_{3dB}} \right)^2} \]  \hspace{1cm} (4-9)

where \( f_{3dB} = 1/2\pi RC \). The output mean-squared noise voltage is

\[ V_{\text{noise,RMS}}^2 = \int_{f_1}^{f_2} \frac{4kTR}{1 + \left( \frac{f}{f_{3dB}} \right)^2} df = NEB \cdot V_{\text{LF, out}}^2 \]  \hspace{1cm} (4-10)

\[ V_{\text{noise,RMS}} = \sqrt{NEB} \cdot \sqrt{V_{\text{LF, out}}^2} = \sqrt{f_{3dB} \cdot \frac{\pi}{2} \cdot 4kTR} = \sqrt{\frac{1}{2\pi RC_{\text{dep}}} \cdot \frac{\pi}{2} \cdot 4kTR} = \frac{kT}{\sqrt{C_{\text{dep}}}} \text{ Volts} \]  \hspace{1cm} (4-11)

Therefore the RMS output voltage noise is “kay tee over cee” and set by the diode’s depletion capacitance.
4.2 SHOT NOISE

In the optical pyrometer ASIC chip there are several devices that contribute to a noise source called shot noise. There are two categories of shot noise that influences the performance of the chip. The first is the noise attributed to the random movement of EHPs, and is called dark current. The other type of shot noise has to do with the collection of photons, and is called photon shot noise. Both the mean-squared values of dark current and photon shot noise combine to increase the noise in the circuit.

Random thermal motion of electrons in a conductor is not the only source of electrical noise present in a circuit. The movement of charge across a potential discontinuity is another noise source, and is commonly referred to as shot noise. Unlike thermal noise, shot noise is independent of temperature, and in comparison with flicker noise is also independent of bandwidth. In high frequency systems, shot noise is usually less dominant than thermal noise.

The term shot noise is also called Schottky noise [15]. This later name was coined by a German physicist (Walter Schottky) who studied the random fluctuations of current in semiconductor devices. Two conditions have to exist for the presence of shot noise. The first condition is that a device must have a potential barrier, and the second is that the potential barrier is the driving mechanism for current. In diodes, a pn junction acts as a barrier that impedes the flow of current. As electrons encounter the barrier, the potential energy starts to increase to a point where the electrons have enough energy to surmount the barrier. The net gain in energy amounts to an increase in the kinetic energy of the electrons. The shot noise is associated with this flow of electrons as a consequence
of this gain in kinetic energy across the potential barrier. Figure 24 shows a pictorial description of shot noise generation in a pn junction diode.

![Figure 24. Shot noise generation [15].](image)

The shot noise PSD is given by

\[
I_{\text{shot}}^2(f) = 2qI_{\text{DC}} A^2 / \text{Hz} \quad (4-12)
\]

Equation (4-12) shows that shot noise has a white spectrum, and therefore is independent of frequency, but is dependent on the charge of an electron and current.

In the optical pyrometer ASIC chip, the circuit element that is the largest contributor to shot noise is the photodiode. The device is reverse biased, so a significant electric potential barrier is generated; however, since the photodiode has a small saturation current due to the thermally generated EHPs while reverse biased, the noise contribution attributed to shot noise is minimal. A small saturation current, hence a small shot noise contribution, is the result of the potential barrier for a reverse biased photodiode being large enough to prevent the thermally generated EHPs from drifting to
the p region [15]. Not all of the electrons are confined to the n region of the photodiode, so the few electrons that do migrate to the p region, and do not recombine, account for the small DC saturation current.

4.2.1 DARK CURRENT

The thermally generated current, resulting from thermal generation in the photodiode's depletion region, is called dark current. The name dark current and saturation current are used to describe the thermally generated carriers in a photodiode and diode respectively. If the dark current is a constant then it can be easily be blocked or removed from the desired signal; however, as mentioned in 4.2, the discrete nature of electrons implies that the signal will fluctuate, therefore the only solution available is to minimize the effect on the photocurrent signal. Dark current is modeled as

\[ I_{\text{noise, dark}}^2(f) = 2qI_{\text{dark}} (A^2/Hz) \]  
(4-13)

The RMS dark current is

\[ I_{\text{dark, RMS}} = \sqrt{2qI_{\text{dark}}B} \ (Amps) \]  
(4-14)

where \( B \) is the bandwidth of the PD.

4.2.2 PHOTON NOISE

Shot noise is not limited to electrons passing over a potential barrier in a semiconductor, but is also inclusive of how photons are received by a photodiode. The
number of photons collected by an instrument, such as a photodiode, follows a Poisson distribution [16]. This is due to the discrete nature of photons, and the uncorrelated events of receiving consecutive photons [16]. The independence of random photon arrival accounts for the shot noise in the photodiode. Photonic shot noise has the same “white” distribution as shot noise, but is only a concern at low light levels. Photonic shot noise is defined as

\[ I_{\text{noise,photon}}(f) = 2qI_{\text{photo}} (A^2/Hz) \]  

(4-15)

The RMS photonic noise current is

\[ I_{\text{photon,RMS}} = \sqrt{2qI_{\text{photon}}B} \text{ (Amps)} \]  

(4-16)

where \( B \) is the bandwidth of the PD. Notice the difference between equations (4-16) and (4-14). The dark current contributes to the shot noise, and is a function of the dark current, or the electrons that are thermally generated in the device; however, the photonic noise is a function of the photocurrent. The photocurrent is the desired signal, but this equation is implying that the photocurrent is not a constant even if the source is producing continuous width (CW) radiation. The desired signal exhibits fluctuations due to the statistical nature of collecting photons.

The fluctuations in the signal current are greater at low light levels since the fluctuations account for a greater percentage of the signal (1000 photons collected with an uncertainty of ±100 (1%) photons, or 1,000,000 photons collected with an uncertainty of ±1000 (0.1%) photons where the uncertainty for a Poisson distribution is \( \sqrt{\bar{n}} \), where \( \bar{n} \) is the average number of photons collected) [17]. The implication of
photonic shot noise on a photodiode is that there is a limitation that exists in receiving photons from a source, and as long as that source is emitting a significant amount of photons, then photonic shot noise minimally impacts the SNR of the system.

The total shot noise is

\[ I_{\text{shot,RMS}}^2 = I_{\text{dark,RMS}}^2 + I_{\text{photon,RMS}}^2 = 2q(I_{\text{dark}} + I_{\text{photo}})B \, (\text{Amps}^2) \]

(4-17)

4.2.3 NOISE EQUIVALENT POWER

An important parameter that often is quoted in photodiode datasheets is the noise equivalent power (NEP). NEP is the optical power required to produce a photocurrent signal that is equivalent to the total shot noise in a photodiode for a particular wavelength of light within a bandwidth of 1 Hz [19]. This is the same as saying that NEP is the required optical power in achieving unity SNR within a bandwidth 1 Hz. The equation for NEP is

\[ \text{NEP} = \frac{P_o}{\sqrt{B}} = \frac{1}{R} \cdot \sqrt{2q(I_{\text{dark}} + I_{\text{photo}})} \, (W/\sqrt{\text{Hz}}) \]

(4-18)

where \( R \) is the responsivity defined by equation (2-4) and restated as

\[ R = \frac{I_{\text{ph}}}{P_o} \]

The photocurrent in the numerator of the responsivity equation is replaced with the equivalent shot noise current per the definition for NEP.
4.3 FLICKER NOISE

Flicker, or (one-over-\(f\)), noise is found in all active devices [18]. The spectrum of flicker noise decreases as the frequency increases. Figure 25 shows an example PSD for flicker noise in a device.

![Figure 25. Flicker noise PSD [18].](image)

Clearly at low frequencies the dominant noise source in any system that contains active devices will almost certainly be flicker noise, and high frequencies, a reasonable assumption for the dominant noise source in most practical systems is either thermal or shot noise (white noise sources).

In the optical pyrometer ASIC chip, the MOSFETS that comprise the current mirrors and feedback amplifiers will contribute the highest amount of flicker noise within the circuit. The drain current will exhibit a flicker as charge carriers move across the gate-oxide interface and become trapped amongst the extra energy states. This trapping and releasing induces the flicker that is more likely to occur at low frequencies [19]. The noise model to describe flicker noise in general is described as
\[
I_1^2(f) = V_1^2(f) = \frac{FNN}{f} A^2/Hz \text{ or } V^2/Hz \quad (4-19)
\]

where \(FNN\) is the flicker noise numerator [8]. For MOSFETS, the \(FNN\) is described as

\[
FNN = \frac{\kappa}{C_{ox}WL} \quad (4-20)
\]

where \(\kappa\) is a process-dependent parameter, and \(C_{ox}\) is the oxide capacitance. In SPICE, the flicker noise numerator is

\[
FNN = \frac{K_F I_D^{AF}}{(C_{ox}^{'L})^2} \quad (4-21)
\]

\[
C_{ox}^{'L} = \frac{\varepsilon_r \varepsilon_0}{t_{ox}} \quad (4-22)
\]

\(K_F\) is the flicker noise coefficient, \(I_D\) is the DC drain current, and \(AF\) is the flicker noise exponent that is assumed to have a typical value of 1 [8, 14]. The \(FNN\) in (4-20) and (4-21) implies that low noise circuits will have MOSFETS with device areas that are large in order to minimize the effects of flicker noise. The mean-squared value is

\[
V_{1f}^2 = \int_{f_1}^{f_2} FNN \cdot \ln f \cdot df = FNN \cdot \ln \frac{f_2}{f_1} \cdot V^2 \quad (4-23)
\]

Considering both the flicker and thermal noise components for the MOSFET, the circuit model is shown in Fig. 26. The overall noise model for the MOSFET is

\[
I_{noise,MOS}^2(f) = I_1^2(f) + I_{R,MOS}^2(f) = \frac{K_F I_D^{AF}}{(C_{ox}^{'L})^2} + \frac{8kT}{3} \cdot g_m \quad (4-24)
\]
4.4 TREATMENT OF NOISE IN IMPROVED TIA CIRCUIT

Recall that the improved TIA circuit is in Fig. 13. Before going right into the analysis of the circuit, a few details regarding noise in current mirrors and how to treat noise in multi-stage amplifiers will make the transitions through the analysis appear seamless. Many times throughout this section the output noise measurement is less important for the interpretation of the effects of noise in the system than the input-referred noise. Input-referred noise cannot physically be measured within a circuit; nevertheless, the information that it conveys gives us a model for how the input signal is affected by the noise. Now the active device can be treated as a noiseless amplifier, and the output signal, from the noise alone, generates the output noise exactly like the actual circuit.

4.4.1 THE TREATMENT OF NOISE IN CURRENT MIRRORS

Figure 27 shows a simple current mirror with the inclusion of the MOSFET noise models for MB1 and M1.
The MOSFET noise model contains the flicker and thermal noise components, and is described in equation (4-24). If the MOSFETs are perfectly matched then the noise from MB1 gets mirrored over to M1. In order to see this, the diode-connected MB1 transistor in Fig. 27 is modified to represent a resistor, and now the circuit is shown in Fig. 28.

![Figure 27. Simple current mirror noise model.](image)

The noise voltage at the gate of MB1 and M1 is the same, and is represented as

\[ v_{n,MB1}^2(f) = v_{n,M1}^2(f) = v_n^2(f) \quad V^2/\text{Hz} \quad (4-25) \]
A diode-connected transistor is modeled as a resistor with resistance $1/g_m$, so, the noise current across the diode-connected transistor is

$$i_n^2(f) = \frac{v_n^2(f)}{g_{m,MB1}^2}$$  \hspace{1cm} (4-26)

Referring this to the output of the current gives

$$v_o^2(f) = g_{m,M1}^2 \cdot i_n^2(f) = g_{m,M1}^2 \cdot \frac{v_n^2(f)}{g_{m,MB1}^2} = v_n^2(f)$$ \hspace{1cm} (4-27)

This implies that the noise from MB1 is mirrored over to the output M1, therefore the total output noise for a simple current mirror is

$$I_{noise,CM}^2(f) = I_{noise,MB1}^2(f) + I_{noise,M1}^2(f)$$ \hspace{1cm} (4-28)

The improved TIA design incorporates a cascode current mirror instead of a simple current mirror. There are several advantages in utilizing a casocde current mirror. One that has already been mentioned is the current gets closer to ideal since the voltage across the output of the mirror remains relatively constant; however, from the standpoint of noise, the cascode current mirror improves the circuit’s SNR. The gain of a cascode current mirror is significantly larger than the gain of the simple current mirror, and the input-referred noise is inversely proportional to the gain, so the noise is reduced and the signal power is increased, therefore the SNR is increased. Figure 29 shows a cascode circuit that includes the noise models for the MOSFETs.
In both the PMOS and NMOS current mirrors the noise from MB1 and MB3 are mirrored over to M1 and M3 respectively; however, something interesting happens with the noise from M2. The noise current from M2 has two possible paths to go. One is through the cascode consisting of the impedance looking into the drain of M2, and the other path is a circulation around M2. The impedance of M2 is much smaller than the impedance of the cascode, so the noise current from M2 simply circulates around M2, and does not contribute to the noise in the rest of the circuit. This is a powerful low noise design technique that also has added benefit of higher gain because of the larger output impedance.

4.4.2 INPUT-REFERRED NOISE IN MULTI-STAGE AMPLIFIERS

The output noise for a single amplifier according to Fig. 30 is
\[ v_{\text{noise}}^2(f) = A^2 v_{\text{noise}}^2(f) \ (V^2/Hz) \quad (4-29) \]

\[ v_{\text{noise}}^2(f) = A^2 v_{\text{noise}}^2(f) \ V^2/Hz \]

Figure 30. Output-referred noise of a single amplifier.

For a circuit with \( N \) amplifiers, in cascade, the output referred-noise is

\[ v_{\text{noise}}^2(f) = (A_1^2 A_2^2 \cdots A_N^2) \cdot v_{\text{noise}1}^2(f) + (A_2^2 \cdots A_{N-2}^2 A_{N-1}^2 A_N^2) \cdot v_{\text{noise}2}^2(f) + \cdots + A_N^2 v_{\text{noise}N}^2 \quad (4-30) \]

The input-referred noise becomes

\[ v_{\text{noise}}^2(f) = v_{\text{noise}1}^2(f) + \left( A_{N-2}^2 A_{N-1}^2 A_N^2 \right) \frac{v_{\text{noise}2}^2(f)}{A_1^2} + \cdots + \frac{A_N^2}{A_1^2 A_2^2 \cdots A_{N-2}^2 A_{N-1}^2} \cdot v_{\text{noise}N}^2 \quad (4-31) \]

This result implicitly says that to minimize the overall noise in the \( N \) cascaded amplifiers, the focus should be reducing the noise of the first stage amplifier.

**4.4.3 PHOTODIODE INPUT-REFERRED NOISE IMPACT**

Figure 31 shows the input-referred noise of an amplifier due to the thermal noise contribution from the biasing circuit of a photodiode. In section 4.1, the model for the
The input noise from the PD was given in (4-11), and is repeated below.

\[
V_{in\text{oise},RMS} = \sqrt{\frac{kT}{C}} \text{Volts}
\]

Consider that the amplifier has a small input impedance, similar to a TIA, so the input-referred noise from the PD divides across the bias resistor and input impedance of the amplifier. Therefore, the RMS noise across the input of the amplifier is

\[
V_{in\text{oise},Rin} = \sqrt{\frac{kT}{C}} \cdot \frac{R_{in}}{R_{in} + R_{bias}} \text{(V)} \quad (4-32)
\]

The noise across the input of the TIA is also expressed as an RMS current from
\[ I_{\text{noise,Rin}} = \sqrt{\frac{kT}{C}} \cdot \frac{R_{\text{bias}}}{R_{\text{bias}} + R_{\text{in}}} = \sqrt{\frac{kT}{C}} \cdot \frac{1}{R_{\text{in}} + R_{\text{bias}}} \] (A) (4-33)

If the active device is a TIA then the expectation is the input impedance is small, so let’s assume \( R_{\text{in}} = 1 \, \Omega \). In choosing an appropriate value for the bias resistance, the bias voltage and reverse current are used from the component datasheets. Table 4-1 shows the effect of PD noise on a noiseless TIA.

<table>
<thead>
<tr>
<th>Company</th>
<th>Year</th>
<th>Part Number</th>
<th>Photodiode Material</th>
<th>Spectral Range (nm)</th>
<th>Depletion Capacitance (pF)</th>
<th>Max. Bias Voltage (V)</th>
<th>Reverse Current (mA)</th>
<th>Bias Resistance (kΩ)</th>
<th>Photodiode Thermal Noise (nV RMS)</th>
<th>Photodiode Noise Current (nA RMS)</th>
</tr>
</thead>
<tbody>
<tr>
<td>THORLABS</td>
<td>2013</td>
<td>FA781</td>
<td>Gallium Phosphide (GaP)</td>
<td>150-1550</td>
<td>1.00</td>
<td>3</td>
<td>2</td>
<td>1.5</td>
<td>2.61</td>
<td>1.36</td>
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<td></td>
<td>2013</td>
<td>FA7800</td>
<td>Silicon (Si)</td>
<td>550 - 1100</td>
<td>3.4</td>
<td>25</td>
<td>5</td>
<td>5</td>
<td>13.43</td>
<td>3.61</td>
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<tr>
<td></td>
<td>2013</td>
<td>FA78000</td>
<td>Silicon (Si)</td>
<td>260 - 1100</td>
<td>0.94</td>
<td>20</td>
<td>5</td>
<td>4</td>
<td>26.27</td>
<td>4.38</td>
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<tr>
<td></td>
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<td>Silicon (Si)</td>
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<td>5</td>
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<td>LASER COMPONENTS</td>
<td>2013</td>
<td>LA1250X</td>
<td>Indium Gallium Arsenide (InGaAs)</td>
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<td>70</td>
<td>108.78</td>
<td>1.22</td>
</tr>
</tbody>
</table>

Table 4-1. PD RMS input-referred noise.

As the depletion capacitance of a PD decreases, the thermal noise increases, and the consequence of this on the system is a reduction in the SNR. For applications that require the sensing of near-infrared (NIR) or infrared (IR) radiation, the choice of PD is limited to InGaAs photodiodes that have extremely small depletion capacitance values, and these types of PDs have the potential of decreasing the SNR of the overall system. Not only does the PD affect the noise, but the biasing resistor also impacts the noise sensitivity. In a TIA, the input-referred noise from the PD decreases as the biasing resistor’s resistance increases; however, an increase in this resistance also reduces the bandwidth since the 3-dB cutoff is inversely proportional to the resistance of the bias resistor. This is another example of the tradeoffs between low-noise design and the effects on a system’s speed and bandwidth.
4.5 IMPROVED TIA CIRCUIT NOISE ANALYSIS

Recall that the improved TIA circuit is shown in Fig. 13. In performing the noise analysis of this circuit, the series-shunt feedback amplifier is ignored since the noise contribution is insignificant when referring the output noise back to the input of the TIA. In the discussion regarding input-referred noise in multi-stage amplifiers, from section 4.4.2, the input-referred noise of the first amplifier has the largest noise contribution, so any attempt in reducing the noise starts here. The noise models for the series-shunt feedback amplifier are not included in the analysis because they contribute the least amount of noise in the circuit. The MOSFET noise in the series-shunt feedback amplifier is reduced by the gain from the previous stages, and therefore will have a miniscule role in the overall noise. Figure 32 shows the model for the input-referred noise, $i_{\text{noise}}^2(f)$, in a TIA. The desired photocurrent signal, $i_{\text{ph}}$, is as an open circuit for the noise analysis.

![Figure 32. TIA noise model.](image-url)
The output noise from the TIA is given below:

\[ v_{\text{onoise}}^2(f) = \left( i_{\text{inoise}}^2(f) + \frac{4kT}{R_f} \right) \cdot R_f^2 \ (Volts^2) \]  

(4-34)

In Fig.33, on the next page, the noise model for the improved TIA circuit is shown. Only the MOSFETs that contribute significant noise are modeled. Notice that the feedback resistance thermal noise model is not shown in the figure. As seen in Eq. (4-34), the thermal noise from the feedback resistor is factored into the overall analysis and has little impact when determining the input-referred noise current \( i_{\text{inoise}}(f) \). Also, the MOSFET noise from the cascode is shown, but will not add any noise into the circuit. Recall the discussion about the treatment of noise in current mirrors from section 4.4.1. Essentially the noise current circulates around the cascode and never leaves since the impedance of the cascode compared to the MOSFET that generates the noise current is significantly larger. The goal is to determine the noise at the node labeled \( v_x \), the output of the first amplifier (the shunt-shunt feedback amplifier). Once the noise at this node is calculated, the input-referred noise current is simply this noise voltage divided by the gain, in ohms, of M2.
The input-referred noise for the improved TIA is

\[ i_{\text{noise}}(f) = \frac{v_{\text{in}}^2(f)}{A_1^2} = \frac{v_{\text{noise1}}^2(f) + v_{\text{noise2}}^2(f)}{A_1^2} \ (A^2/Hz) \quad (4-35) \]

given that

\[ A_1^2 = (r_{o1}||R_{\text{cas}})^2 \ (\Omega)^2 \quad (4-36) \]

The output noise at the drain of M6 is called \( v_{\text{onoise2}}(f) \) and is defined as

Figure 33. Improved TIA noise model.
\[ v_{\text{noise}2}^2(f) = \left( I_{\text{noise},M4}^2(f) + I_{\text{noise},M5}^2(f) \right) \cdot (r_{o4}||r_{o5})^2 \quad (V^2/Hz) \quad (4-37) \]

Referring the output noise back to the input gives \( v_{\text{noise}2}^2(f) \)

\[ v_{\text{noise}2}^2(f) = \frac{v_{\text{noise}2}^2(f)}{A_2^2} = \frac{\left( I_{\text{noise},M4}^2(f) + I_{\text{noise},M5}^2(f) \right) \cdot (r_{o4}||r_{o5})^2}{g_{m4}^2 \cdot (r_{o4}||r_{o5})^2} = \frac{\left( I_{\text{noise},M4}^2(f) + I_{\text{noise},M5}^2(f) \right)}{g_{m4}^2} \quad (V^2/Hz) \quad (4-38) \]

The output noise from the first stage amplifier, \( v_{\text{noise}1}^2(f) \), is calculated as

\[ v_{\text{noise}1}^2(f) = \left( I_{\text{noise},M1}^2(f) + I_{\text{noise},M3}^2(f) \right) \cdot (r_{o1}||R_{\text{cas}})^2 \quad (V^2/Hz) \quad (4-39) \]

Plugging (4-39), (4-38), and (4-36) into (4-35) gives

\[ i_{\text{noise}}^2(f) = \frac{v_{\text{noise}}^2(f)}{A_1^2} = \]

\[ \frac{\left( I_{\text{noise},M1}^2(f) + I_{\text{noise},M3}^2(f) \right) \cdot (r_{o1}||R_{\text{cas}})^2 + \left( I_{\text{noise},M4}^2(f) + I_{\text{noise},M5}^2(f) \right)}{g_{m4}^2 (r_{o1}||R_{\text{cas}})^2} \quad (4-40) \]

\[ i_{\text{noise}}^2(f) = I_{\text{noise},M1}^2(f) + I_{\text{noise},M3}^2(f) + \cdots \]

\[ + \left( I_{\text{noise},M4}^2(f) + I_{\text{noise},M5}^2(f) \right) \quad (A^2/Hz) \quad (4-41) \]

The noise current in M1 and M3 have two components. Recall that the noise from the current mirrors gets referred over to the output of the mirror.
\[ I_{\text{noise,M1}}^2(f) = I_{\text{noise,MB1}}^2(f) + I_{\text{noise,M1}}^2(f) \quad (A^2/\text{Hz}) \quad (4-42) \]

\[ I_{\text{noise,M3}}^2(f) = I_{\text{noise,MB3}}^2(f) + I_{\text{noise,M3}}^2(f) \quad (A^2/\text{Hz}) \quad (4-43) \]

Equation (4-40) shows that the input-referred noise for the TIA follows the assertion from section 4.4.2 that

\[ i_{\text{noise}}^2(f) = i_{\text{noise1}}^2(f) + \frac{i_{\text{noise2}}^2(f)}{A_1^2} \quad (A^2/\text{Hz}) \quad (4-44) \]

To complete the entire noise analysis, the feedback resistance is now included, so the output noise is

\[ v_{\text{noise}}^2(f) = \left[ \left( I_{\text{noise,M1}}^2(f) + I_{\text{noise,M3}}^2(f) + \frac{(I_{\text{noise,M4}}^2(f)+I_{\text{noise,M5}}^2(f))}{g_m A_4 (r_{01}||R_{\text{cas}})^2} \right) + \frac{4kT}{R_f} \right] \times R_f^2 \quad (4-45) \]

In order to reduce the noise in the TIA circuit attention must be drawn to \( I_{\text{noise,M1}}^2(f) \) and \( I_{\text{noise,M3}}^2(f) \). Since an increase in thermal noise is proportional to the transconuctance of a MOSFET, the obvious choice is to reduce this value in order to reduce the noise; however, the speed of a MOSFET is also proportional to the transconductance, so decreasing this value will also have the latent effect of reducing the speed of the TIA. For the flicker noise, an obvious choice is to use larger channel areas to minimize noise, but this also reduces the speed of the TIA since the speed of a MOSFET is inversely proportional to the channel length. The point to be made here is that tradeoffs need consideration, and if low-noise is more important than speed, then the techniques mentioned are more than adequate to employ in the design process.
Figure 34 shows the noise analysis schematic for the improved TIA, and Fig. 35 shows the simulation results for the thermal noise in the MB1 and M1 MOSFETs.

Figure 34. TIA noise analysis schematic.

Figure 35. Voltage spectral density noise plot for MB1 and M1.
This plot shows that there is slightly more thermal noise contributions to the output noise from M1 than MB1. Recall that the noise in a current mirror gets referred over to the output of the mirror, so the noise in M1 is approximately twice as much since M1 is the output and MB1 is the input of mirror. Figure 36 shows the thermal noise in the TIA due to MOSFETs M1 through M5.

![Figure 36. Thermal noise contribution in the TIA due to MOSFETs M1 through M5.](image)

Notice that the noise contributions from M2, M4, and M5 are significantly smaller than the contributions from M1 and M3. M2 is the cascode, and therefore the noise circulates around M2 without much effect on the TIA circuit. The input-referred noise at M4 and M5 are inversely proportional to the square of the gain from the first stage amplifier, and because the gain from the first stage is large, the noise contributions from M4 and M5 MOSFETs are small.
CHAPTER 5 – SIMULATION AND TESTING RESULTS

5.1 IMPROVED TIA FINAL SIMULATION RESULTS

Prior to sending the TIA chip for fabrication, a final simulation was done on the improved TIA circuit that also includes the model for the photodiode. This is an important step in the verification process to evaluate the performance of the TIA, and at the very least will give the best case achievable results. Recall from Chapter 3 that the TIA is composed of bias circuitry, a shunt-shunt feedback amplifier, and a series-shunt feedback amplifier. The analysis and simulation was originally done at the transistor level. Now the analysis is focused on one level of abstraction up from the transistor level, and the TIA is treated as a black box. In this section a DC, transient, and noise simulation is performed on the TIA. The primary difference between these simulations done in this chapter as compared to Chapter 3 is the additional circuitry that interfaces with the input of the TIA. Models for the photodiode and parasitics appear in the schematics to create a practical realization of the optical pyrometer ASIC. Figure 37 shows the schematic used in simulating the DC analysis of the TIA circuit. The PD is not included in the DC sweep since it is AC coupled to the input of the TIA.
A DC sweep of the input and output terminals are displayed in Fig. 38 and Fig. 39 respectively.

The expectation is that the DC voltage at the input pin should be close to 1.4 V and vary as little as possible with changes in the input current indicating low TIA input resistance.
Notice at the output, there is a DC offset. Any current with a peak-to-peak value of 110 μA or greater, and the DC offset at the output saturates around 2 V.

The schematic for the transient analysis is shown in Fig.40, and includes the model for the photodiode (PD).

Figure 39. Output terminal DC sweep of the improved TIA.

Figure 40. Improved TIA circuit schematic with PD model.
Notice that there are several capacitors and inductors used at the input and output terminals of the TIA. The 100pF capacitor is an AC coupling capacitor to block any of the DC voltage at the input terminal. This capacitor prevents the input pin of the TIA from interfering with the biasing of the PD. It also prevents the biasing circuitry from driving the input of the TIA. Essentially the desired signal at the input terminal will have only an AC current component. The 2.5 pF capacitor models the reverse-biased photodiode (PD), and the 40 V DC power supply with the 100 kΩ input resistor functions as the bias to the PD. Also notice the 10 nH and 1 pF capacitors at both the input and the output terminals. These were included in the schematic to model the parasitics of any wires or copper traces that are used for connecting and interfacing other devices to the TIA. The input pulse parameters are described in Table 5-1.

<table>
<thead>
<tr>
<th>Input Pulse Parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>Delay Time</td>
</tr>
<tr>
<td>Fall Time</td>
</tr>
<tr>
<td>Initial Current</td>
</tr>
<tr>
<td>Period</td>
</tr>
<tr>
<td>Pulse Current</td>
</tr>
<tr>
<td>Pulse Width</td>
</tr>
<tr>
<td>Rise Time</td>
</tr>
</tbody>
</table>

Table 5-1. Input pulse parameters.

A delay time of 1005 ns is specified to allow enough warmup time for the TIA. This allows the DC operational point to reach a steady-state. The pulse current contains a parameter value of \{I_{peak}\}, and allows the user to specify a list of values for SPICE to execute from the the layout view of the schematic. In this simulation, the name of the list is I_{peak}, and the values for I_{peak} appear in the SPICE command below the schematic in Fig.39 (.step param I_{peak} list ). Since SPICE ignores any directive that begins with an
asterisk, the current simulation will generate an output voltage given the peak input
currents of 100nA, 200nA, 500nA, and 1μA. Figure 41 shows the output of the TIA
given the input currents from the list Ipeak.

Figure 41. Output signals produced by Ipeak currents.

For the noise simulation, the schematic looks identical to the transient analysis
schematic; however, the SPICE directive is different. The simulation schematic is shown
in Fig. 42.

Figure 42. Improved TIA noise analysis schematic.
The SPICE directive states that the noise measurement is made at the output of the TIA. Notice that the Ipeak list is not specified anywhere in the SPICE directive. The reason for this is noise measurements are made without an input signal because the only interest here is the measurement of noise and not the input signal in addition to the noise. Since the input signal is a current, the input pin of the TIA is treated as an open circuit (Hi-Z). If the input signal was a voltage then the input terminal is pulled to ground. The output noise voltage spectral density plot is shown in Fig. 43.

![Figure 43. Output noise measurement for the Improved TIA circuit.](image)

The output noise RMS voltage is found by integrating the output noise voltage spectral density from the starting frequency (1 kHz) to the ending frequency (10 GHz). In LTspice, the RMS output noise voltage is found by pressing CTRL + left mouse button on V(onoise). The output noise RMS voltage is in Fig. 44.
The noise simulation also generates a gain versus frequency plot, and is shown in Fig.45.

Therefore the input-referred noise is

\[
I_{\text{noise,RMS}} = \frac{V_{\text{noise,RMS}}}{A_{CL}} = \frac{2.77 \text{ mV}}{13 \text{ k}\Omega} = 213 \text{ nA RMS}
\]  

(5-1)

Notice from Fig.45 that the best closed-loop gain that is expected from the TIA is 13 k\(\Omega\), but ideally the expectation is that the gain is equivalent to the feedback resistance (25 k\(\Omega\)). A natural question is what happened to half of the gain? One way to understand what is happening with the TIA lies with the closed-loop gain. An expression for the closed-loop gain is
\[ A_{CL} = \frac{A_{OL}}{1 + \beta A_{OL}} \quad (5-2) \]

The closed-loop gain reduces to

\[ A_{CL} = \frac{1}{1 + \frac{1}{A_{OL}}\beta} = \frac{1}{\beta} \quad (5-3) \]

as \( A_{OL} \to \infty \). It was previously determined from Chapter 3 that the value for the feedback factor, \( \beta \), is \( \beta = -1/R_f \); where \( R_f \) is the feedback resistance.

\[ \therefore A_{CL} = R_f = 25 \text{ k}\Omega \quad (5-4) \]

This is the best gain that is achievable with this TIA. The problem with this is that the open-loop gain for the TIA is certainly not infinitely large. The actual open-loop gain is determined from simulation, so the schematics below demonstrate how to measure the open-loop gain for the Improved TIA. Figure 46 is the schematic for determining the open-loop gain of the shunt-shunt feedback amplifier.
Figure 46. Open-loop gain of the shunt-shunt feedback amplifier with $R_f = 25 \, k\Omega$.

Figure 47 shows the schematic for determining the open-loop gain of the series-shunt feedback amplifier.
The series-shunt feedback amplifier stage uses an AC voltage source as the input stimulus since the input mixing is voltage; however, the shunt-shunt feedback amplifier uses an AC current for an input stimulus because the input mixing is current. The inductors isolate the AC signals from feeding back to the input while maintaining the same DC biasing. An inductor between the amplifier stages also isolates the analysis to a single stage. Capacitors are utilized to provide an AC path to ground. The plot of the gain from the shunt-shunt feedback amplifier is shown in Fig. 48.

Figure 47. Open-loop gain of the series-shunt feedback amplifier.
The results of the simulation in Fig.46 show that the open-loop gain for the shunt-shunt feedback amplifier is $A_{OL,shunt-shunt} = 62 \, k\Omega$. Figure 49 shows the open-loop gain of the series-shunt feedback amplifier. The closed-loop gain of the shunt-shunt feedback amplifier is

$$A_{CL,shunt-shunt} = \frac{A_{OL}}{1 + \beta A_{OL}} = \frac{62 \, k\Omega}{1 + \frac{1}{25 \, k\Omega} \cdot 62 \, k\Omega} = 17.8 \, k\Omega$$

(5-5)
According to the simulation results in Fig. 49, the open-loop gain of the series-shunt feedback amplifier is $A_{OL,series-shunt} = 7.7$. Therefore, the closed-loop gain of the series-shunt feedback amplifier is

$$A_{CL,series-shunt} = \frac{A_{OL}}{1 + \beta A_{OL}} = \frac{7.7}{1+1.77} = 0.89 \quad (5-6)$$

Therefore, the open-loop gain of the improved TIA is

$$A_{CL} = A_{CL,shunt-shunt} \cdot A_{CL,series-shunt} = 17.8 \, k\Omega \cdot 0.89 = 15.8 \, k\Omega \quad (5-7)$$

As expected, since the open-loop gain of the TIA is not infinitely large, the closed-loop gain will never be 25 $k\Omega$.

5.2 IMPROVED TIA CIRCUIT TEST RESULTS

The improved TIA circuit was fabricated through MOSIS on a multi-project wafer. The deliverable consists of a ceramic forty pin dual inline package (DIP) chip with five unique TIAs. A picture of the bare die chip is shown in Fig. 50.
A schematic of the test circuit is shown in Fig. 51. The TIA is modeled as an operational amplifier (op-amp), so the details of the improved TIA circuit at the transistor level are omitted.
The “CTIA_v4” nomenclature in Fig. 51 is the fourth version TIA on the chip out of five unique TIAs. The equipment that was used to test the TIA circuit is shown in Table 5-2.

<table>
<thead>
<tr>
<th>Equipment</th>
<th>Name</th>
<th>Model#</th>
</tr>
</thead>
<tbody>
<tr>
<td>DC Power Supply</td>
<td>Agilent</td>
<td>E3649A</td>
</tr>
<tr>
<td>Pulse Generator</td>
<td>Stanford Research Systems</td>
<td>DG535</td>
</tr>
<tr>
<td>Pulse Generator</td>
<td>Hewlett Packard</td>
<td>8082A</td>
</tr>
<tr>
<td>Oscilloscope</td>
<td>Rhode &amp; Schwarz</td>
<td>RTO 1024</td>
</tr>
<tr>
<td>Multimeter</td>
<td>Fluke</td>
<td>77</td>
</tr>
<tr>
<td>Spectrum Analyzer</td>
<td>Hewlett Packard</td>
<td>8563A</td>
</tr>
<tr>
<td>50 ohm feedthru terminantor</td>
<td>EG&amp;G</td>
<td>n/a</td>
</tr>
</tbody>
</table>

Table 5-2. Equipment fielded for TIA test.

A picture of the test bench is shown in Fig. 52.

![Test bench](image)

Figure 52. Test bench.

Figure 53 is a top level view of the DIP connected to the proto-board. One drawback in using a DIP package for high frequency design is the bonding wires from the chip to the pads are long enough to increase the parasitic impedance resulting in poor impedance.
matching. The poor impedance control could result in the degradation of the output response to current pulses with fast rise times (several nanoseconds).

\[ i_{\text{in}}(t) = \frac{v_{\text{pulse}}(t)}{R_{\text{in}}} \] (5-8)

Throughout the testing, \( v_{\text{pulse}} \) or \( R_{\text{in}} \) were adjusted in order to produce a large enough current. A coupling capacitor is utilized to isolate the pulse generator from the input of the TIA. Since the pulse generator is terminated with 50 ohms, and the input impedance of the circuit is much larger than 50 ohms, a 50 ohm feedthru is connected in between the pulse generator and \( R_{\text{in}} \) to reduce the reflections caused by an impedance mismatch. The

Figure 53. Top level view of DIP.

output of the TIA circuit is connected to an oscilloscope with 50 ohm coupling, and therefore a 50 ohm feedthru is not needed.

Two different types of pulse generators were fielded in order to test the TIA with input currents that have large pulse widths (>100 ns) and short pulse widths (<100 ns). The Stanford Research Systems DG535 produced a \( v_{\text{pulse}}(t) \) at an amplitude of \(-11 \, V_{pp}\) with a pulse width of 800 ns, and the Hewlett Packard 8082A generated a \( v_{\text{pulse}}(t) \) at an amplitude of \(-5 \, V_{pp}\) with pulse widths in the tens of nanoseconds. Both pulse generators have the ability in generating pulses with rise times of 1 ns or more. The drawback in fielding the 8082A pulse generator is that signal amplitudes were limited to \(-5 \, V_{pp}\), so to get a meaningful signal through the amplifier, the input resistor was reduced from 100 k\( \Omega \) to 10 k\( \Omega \). Figures 54 through 56 show the input pulses for the DG535 and 8082A that were used in creating the input current pulses. All of the input voltage signals were falling-edge pulses. As a result, the output pulses will have a rising-edge since the output of the TIA is 180° out of phase with the input. The screen shots were taken directly from the Rhode & Schwarz RTO 1024 oscilloscope.
At 5x attenuation, the actual input voltage peak-to-peak is -11 V with the DG535 pulse generator.

Figure 54. DG535 input voltage pulse #1 at 5x attenuation and 844 ns pulse width.

Figure 55. 8082A input voltage pulse #2 at <5ns pulsewidth.
Notice in Fig. 56 the same pulse generator was used, but one signal appears to behave as a square wave, and has a pulse width of 5 ns; however, the pulse in Fig. 55 is not a square wave, but has a pulsewidth of approximately 2 ns.

The output pulses are shown in Figures 57 through 60.
Figure 57. Output pulse #1.

Figure 58. Output pulse #2.
Table 5-3 displays the theoretical and measured results for different input stimuli.
There are several points regarding these results that need addressing. Output pulse #1 and #2 corresponds with the Input pulse #1 generated from the DG535 and Input pulse #2 generated from the 8082A respectively. Notice that the output signal in Fig. 58 is an order of magnitude smaller than the signal in Fig. 57, but the feedback resistance for input pulse #1 is almost five times smaller. The expectation is that even for a smaller input pulse current with a significantly larger feedback resistor, the gain for output pulse #2 should be approximately twice as much the output pulse #1. An explanation for this discrepancy lies with the DC output voltage. Output pulse #2 is starting close to ground (there is a measured 7 mV offset), and with a small offset, the circuit is barely driving the 50 ohm load of the oscilloscope, and therefore there is not much gain. From the DC sweep of the output voltage in Fig. 37, the expectation is that the minimum DC offset is approximately 300 mV, but the actual measured DC offset is an order of magnitude smaller. One possible reason for this occurrence is a mismatch in the devices. The improved TIA schematic in Fig. 13 is again shown in Fig. 61 with a zoomed in shot of the current mirror circuitry.

Table 5-3. TIA test theoretical and measured results.

<table>
<thead>
<tr>
<th>Input Pulse #</th>
<th>Output Pulse #</th>
<th>Input Pulse Voltage (Volts peak-to-peak)</th>
<th>Input Pulse Current (μA peak-to-peak)</th>
<th>Feedback Resistance (kΩ)</th>
<th>Ideal Open-Loop Gain (kΩ)</th>
<th>Ideal Output Voltage Pulse (mVolts peak-to-peak)</th>
<th>Measured DC Input Voltage (V)</th>
<th>Measured DC Output Voltage (mV)</th>
<th>Measured Output Voltage Pulse (mVolts peak-to-peak)</th>
<th>Measured Open-Loop Gain (kΩ)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1</td>
<td>1.1</td>
<td>100</td>
<td>100</td>
<td>10</td>
<td>100</td>
<td>1.1</td>
<td>10</td>
<td>12</td>
<td>2.0</td>
</tr>
<tr>
<td>2</td>
<td>2</td>
<td>.3</td>
<td>100</td>
<td>50</td>
<td>.5</td>
<td>10</td>
<td>1.5</td>
<td>7</td>
<td>10</td>
<td>2.00</td>
</tr>
<tr>
<td>3</td>
<td>3</td>
<td>.5</td>
<td>100</td>
<td>50</td>
<td>10</td>
<td>10</td>
<td>1.5</td>
<td>7</td>
<td>10</td>
<td>2.00</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>.3</td>
<td>100</td>
<td>50</td>
<td>10</td>
<td>10</td>
<td>1.5</td>
<td>7</td>
<td>10</td>
<td>2.00</td>
</tr>
</tbody>
</table>

83
The presumption is that the gate potential of M1 and M3 remain constant under normal operating conditions. M1 and M3 are the current mirrors and they need to adjust the current supply as the feedback resistance changes. As the feedback resistor size is increased, for high gain, the amount of current that is fed through that resistor decreases requiring larger changes in the output voltage. This results in the failure of the series-shunt feedback amplifier which causes the overall design to fail. The way to simulate this behavior in the current mirrors is to change the gate potential with one of the mirrors, and verify what happens at the output of the series-shunt feedback amplifier. The entire circuit with this change is shown in Fig. 62.

Figure 61. Improved TIA schematic with emphasis on the current mirror.
The transient analysis simulation for the output is displayed in Fig. 63.

The output DC voltage is now at 50 mV, but the decrease in gain is severe. The change in output voltage from the DC offset is approximately 2 mV. Compare this result with the 15 mV change in output voltage from Fig. 41. Another issue is the current mirror...
sensitivity to a mismatch in MOSFETs. If the channel width of M1 is one micrometer different then the channel width of MB1, the change in the output is drastic. The same reasoning can easily apply to the MB3 and M3 transistors. Figure 64 shows the output voltage with a one micrometer increase in the channel width of M1, and Fig. 65 shows the same output with a one micrometer decrease in the channel width of M1.

![Figure 64. Transient analysis results of a 1 μm increase in the channel width of M1.](image)

With a 1 μm increase in the channel length of M1 causes the DC offset at the output of the TIA to change to 49 mV, and the gain has also been hampered. In this particular case, the TIA is a unity-gain device.
Look at what happens to the TIA when M1 has a 1 μm decrease in the channel width.

Now the DC offset voltage is approximately 712 mV, and the maximum change in voltage is 15 V/V. The implication is the lack of balance between the biasing and the feedback resistor is causing the current mirrors to fight against each other, and therefore shutting off the series-shunt feedback amplifier.

The noise measurement was taken with a Hewlett Packard 8563 Spectrum Analyzer. Recall that in order to take a proper noise measurement for the TIA, leave the input pin opened (Hi-Z), so that only the noise and not the desired signal is actually measured. A picture showing the output noise of the TIA is in Fig. 66.

Figure 65. Transient analysis results of a 1 μm decrease in the channel width of M1.
The picture in Fig. 66 shows the horizontal axis is frequency (Hz), and the vertical axis is in RMS voltage. A sweep of the output noise starts at 0 and ends at 10 MHz. The resolution bandwidth for this particular measurement is $f_{res} = 2 \text{ MHz}$. Figure 66 shows the flicker noise ($1/f$) roll off, and according to the marker, the knee frequency is at approximately 5 MHz. The RMS voltage at the one-over-f knee frequency is 68 $\mu$V according to the on-screen marker. To determine the output noise power spectral density, the resolution bandwidth and the output noise RMS voltage are needed. The equation is given by

$$V_{noise}^2(f) = \frac{V_{noise,RMS}^2}{f_{res}} = \frac{(68 \, \mu V)^2}{2 \, \text{MHz}} = 2.31 \times 10^{-15} \, V^2/\text{Hz} \quad (5-9)$$

The voltage spectral density is given by
\[ Voltage \ Spectral \ Density = \sqrt{PSD} = \sqrt{2.31 \times 10^{-15} V^2/Hz} = 48.1 \, nV/\sqrt{Hz} \]

\[ (5-10) \]

The input-referred RMS noise is

\[ I_{\text{noise,RMS}} = \frac{V_{\text{noise,RMS}}}{A} = \frac{68 \, \mu V}{23.1 \, k\Omega} = 2.94 \, nA \, RMS \]

\[ (5-11) \]

This is approximately two orders-of-magnitude smaller than what was shown in equation 5-1. The reason for the discrepancy is the series-shunt feedback amplifier is essentially turned off as a result of the feedback altering the biasing current.

### 5.3 TIA FINAL DESIGN

The improved TIA demonstrates the challenges involved in designing a suitable current-to-voltage amplifier for the optical pyrometer ASIC. One reason for the lack of robustness of the improved TIA lies with the relationship between the biasing and the feedback network. Any redesign will have to address the issue of isolating the feedback network effects from the DC biasing. One topology that does this is shown in Fig. 67.
The final TIA circuit has a number of different features that address the shortcomings from the previous design. One of the problems with the improved TIA was the inability to set the biasing current, and because the bias point was dependent on the feedback network, not having the control over this parameter meant an asymmetrical voltage swing. This implies that the gain of the TIA was not only dependent on the feedback resistance, but dependent on the relationship between the feedback and bias point. Here is how that problem was corrected. An off-chip resistor, or potentiometer will set the bias current as seen in Fig. 67 with a pin labeled Rbias. This pin allows the user to set the bias current, $I_{bias}$, across the folded-cascode current mirrors, the differential pair amplifier, and the the series-shunt feedback amplifier. More control over the biasing in the TIA will prevent the problems with the feedback and bias relationship. A folded-cascode current mirror structure is utilized to better match the bias current in the PMOS and NMOS current mirrors. The series-shunt feedback amplifier at the output is identical.
to the one used in the improved TIA; however, the ambiguity with the input voltage signal to the series-shunt amplifier in the previous design was one of the reasons that a failure occurred in the rest of the circuit, so understanding the bias current behavior at the output and input is crucial in determining the success of the overall TIA. Figure 68 shows the TIA at higher level of abstraction. The transistor-level details are kept hidden.

![Final TIA op-amp schematic](image)

Figure 68. Final TIA op-amp schematic.

Now that the biasing resistor is set to give the user more control of where to set the TIA’s quiescent point, the next problem is determining the added resistance needed at the noninverting pin of the TIA in Fig. 68. Looking back at Fig. 67, the output of the TIA has two DC currents flowing into 50 ohm load. The total current summing at the output node is

\[ I_{O,DC} = I_{bias} + 8 \cdot I_{bias} \]  

(5-11)
Figure 67 shows that the PMOS device connected at the output via the drain terminal has eight times the width, and therefore will have approximately eight times the bias current. If the DC output current is driving a 50 ohm load, or oscilloscope, then the offset voltage becomes

\[ V_{offset} = 9I_{bias} \cdot 50 = 450 \cdot I_{bias} \]  

(5-12)

To balance this DC voltage at the output of the TIA, the input pin of the TIA also needs to have an equivalent \( V_{offset} \), so if a 450 Ω resistor is placed on the noninverting to ground, then another \( V_{offset} \) appears on that pin, and therefore the offset voltage also appears on the input pin. Since the potential difference between the noninverting pin and the output are identical, no DC current will flow through the feedback resistance, and therefore the relationship between the feedback and biasing are no longer intertwined.

Figure 69 is the schematic and DC analysis of the output voltage versus input current respectively. This will aid in demonstrating where the amplifier is operating, and the amount of gain that is expected.
Clearly with only 1 μA of peak current through the TIA with a 5 kΩ bias resistor and 100 kΩ feedback resistance, there is expectation of large gain. A peak input current pulse of 5 μA with a 100 kΩ feedback resistor will give approximately 100 kΩ of gain according to Fig. 70.

Figure 69. Final TIA DC analysis schematic.

Figure 70. Final TIA DC analysis gain expectation with an $R_{bias} = 5k\Omega$. 
Increasing the $R_{bias}$ resistance will improve the performance of the TIA. Figure 71 shows the transient analysis results for an $R_{bias} = 5 \, k\Omega$.

![Figure 71. Final TIA transient analysis with an $R_{bias} = 5 \, k\Omega$.](image)

Clearly with a larger bias resistance the response and gain improves. Figure 72 is a plot of the output voltage with an $R_{bias} = 20 \, k\Omega$.

![Figure 72. Final TIA transient analysis with an $R_{bias} = 20 \, k\Omega$.](image)

Notice that the output voltage has an undershoot. Now what is happening to the TIA as the current source is providing too much current to the amplifiers is the TIA is at the edge of instability. At this point, the TIA is marginally stable, and any increase in the current
will force it into an unstable state. Figure 73 shows a transient analysis with a feedback resistance of 25 kΩ, and an $R_{bias} = 2 kΩ$. This demonstrates a fast pulse response.

Figure 73. Final TIA transient analysis with an $R_{bias} = 2 kΩ$, and $R_f = 25 kΩ$.

Figure 74 is a plot of the final TIA closed-loop gain with a feedback resistance of 100 kΩ.

Figure 74. Final TIA closed-loop gain with an $R_f = 100 kΩ$.

For this TIA, the unity-gain bandwidth occurs at approximately 2.5 GHz. A plot of the output noise power spectral density is in Fig. 75.
The RMS output noise voltage is 4.7 mV, so the input-referred noise RMS current is

\[ I_{\text{noise, RMS}} = \frac{V_{\text{noise, RMS}}}{A_{\text{CL}}} = \frac{4.7 \text{ mV}}{95 k\Omega} \approx 50 nA \text{ RMS} \quad (5-13) \]

5.4 TRANSIMPEANCE AMPLIFIER LAYOUT

The key element in the design of the optical pyrometer ASIC is the design of the transimpedance amplifier (TIA). Chapters 3 discussed two different types of TIAs, one that was referred to as a generic TIA, and the other called an improved TIA. The improved TIA addressed the shortcomings with the open-loop gain of the generic model; however, the improved TIA was sensitive to any mismatch in the biasing circuitry, so that design is not suitable for the optical pyrometer ASIC. The end of Chapter 5 discusses a viable option for a practical TIA. Figure 76 is the layout of the final TIA, and Fig. 76 is the 1.5 mm × 1.5 mm chip layout which included 4 TIAs.
The chip in Fig. 77 consists of four TIAs. Two of the TIA have a 450 Ω bias resistor on chip while the other two require external bias resistors. The chips are fabricated with a C5 Process (On Semiconductor 500 nm) with two polysilicon layers and 3 metal layers.
CHAPTER 6 – CONCLUSIONS AND FUTURE WORK

The infrared optical pyrometer ASIC will consist of a 16 channel linear photodiode array and a folded-cascode differential TIA with a gain of 100 kΩ, a bandwidth of 30 MHz, and an input-referred noise current of 50 nA RMS. Two different topologies were designed and analyzed, but ultimately the only viable option is the Final TIA circuit. The key element in the Final TIA design was the use of a technique called replicative biasing to ensure minimal DC leakage through the feedback network. Once a relationship was identified between the biasing and feedback, the Final TIA appeared to be a more practical consideration. The simulations have shown promise, and the chip is to be fabricated in November of 2013. The anticipated testing date is the middle of December.

Future work also includes investigating ways to further reduce noise while improving bandwidth, and also requires extensive testing of the final TIA prior to its implementation within the optical pyrometer ASIC. The chip design gives us the ability to test the performance of each TIA for several different scenarios simultaneously. Testing will require the in-house fabrication of a PCB that will include a 16 photodiode linear, the TIA chip, and high frequency 50 ohm SMA connectors that connect directly to 16 channels of an off-chip digitizer. The PCB will route the power, off-chip bias resistor, feedback resistor, and I/O signals of the TIA chip. This setup will make the testing of four TIAs easier while at the same time minimizing the effects of parasitics from protoboarding. In future generations of the infrared optical pyrometer ASIC, the reduction in TIA power will be essential in minimizing the thermal load on the photodiode array. One drawback in using the Final TIA over the Improved TIA is the
significant power draw of the Final TIA. Going from a single-ended input amplifier to a differential amplifier implies an increase in the dissipated power. One way to potentially reduce the thermal load on the photodiodes is to multiplex the PD signals onto a single TIA chip. An ADC is another option as an add-on to the optical pyrometer by acting as an on-board digitizer thereby completing the first prototype chip to be fileded in the next shock physics experiment.
REFERENCES


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